MV001 - Globular Shouldered Jar

An Exploration of Precision
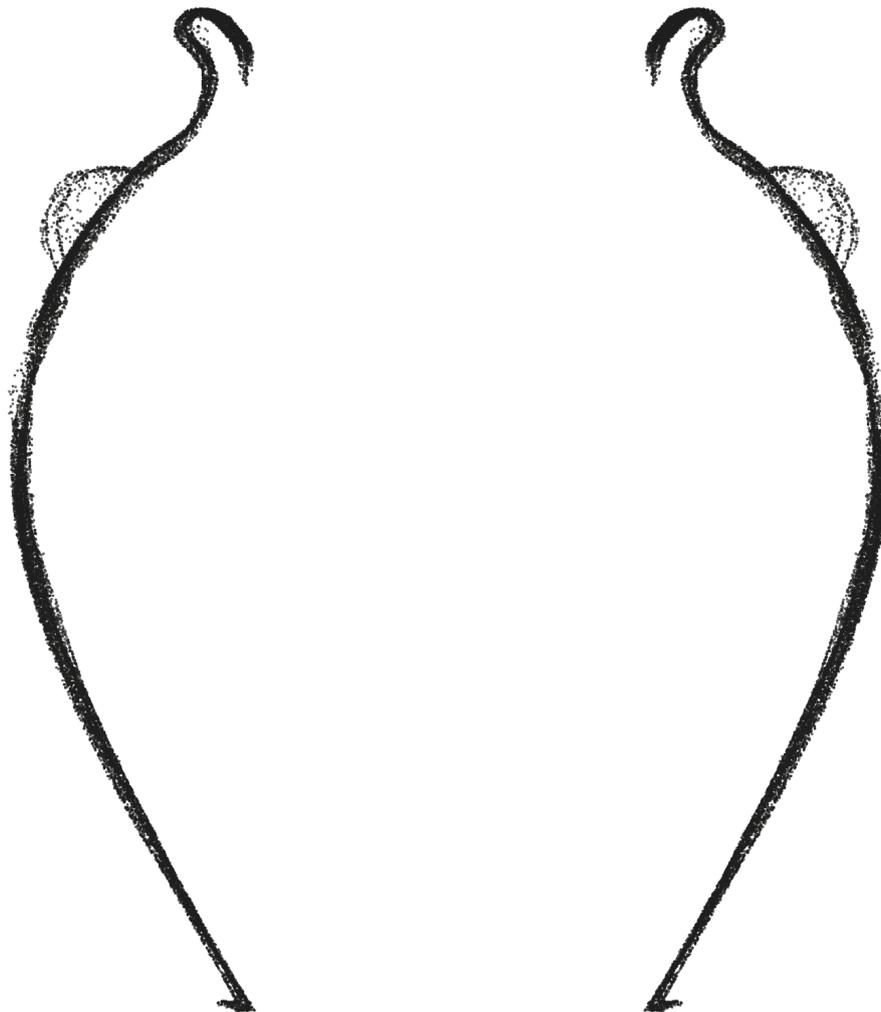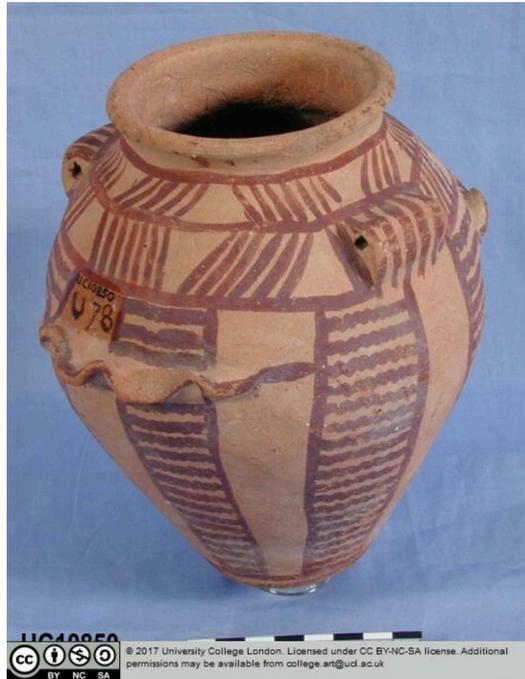
Contents

Artifact Information

Artifact Data

Collection	Petrie Museum of Egyptian Archaeology
Provenance[1]	Petrie Museum of Egyptian Archaeology
Provenience[2]	Unknown
Attribution	Naqada II

Museum information

Ref.	LDUCE-UC10850
Description	Decorated pot, type D 2 k; wavy handled. From Hu tomb U 78.
URL	https://collections.ucl.ac.uk/Details/collect/14969

Maijers vessel classification[3]

Short classification	Globular Shouldered Jar
Long classification	The vessel is created in a closed form classified as a globular jar with a shouldered shape, it has a footed base and a raised blunt rim.

Physical properties

Precision score[4]	1.93	
Height (approximate)	178 mm	7.01 in
Width (approximate)	166 mm	6.54 in
Material	Pottery	
Mohs Hardness[5]	Unknown (Pottery)	
Weight		

Scan information

Source	Scanned by Artifact Foundation
Source file name	UC10850_base_0.09_1.stl
Scan method	Laser
Scanner	FreeScale Combo+
Rated scan accuracy	36 μm | 1.47 thou
Scan date	2024-10-14
Scanned by	Károly Póka
Mesh decimation	None, raw scan file used in the analysis
Number of vertices	15 364 663
Mesh density[6]	37 μm | 1.44 thou
Max vertex distance	154 μm | 6.064 thou
Min vertex distance	0 μm | 0.000 thou
Vertices per cm2	18 733 (approximated)
Vertices per in2	120 857 (approximated)

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[1] The verifiable chain of custody of an artifact

[2] The location or site where an artifact was recovered

[3] Vessel artifact classification developed by W. Arnold Maijer and described in his publication Masters of Stone, ISBN 978-90-829212-0-5

[4] The precision score metric is described in Precision Score Of The Artifact, p. 40

[5] The Mohs scale is an ordinal scale, from 1 to 10, describing the materials resistance to abrasion (the ability of harder material to scratch softer material)

[6] Median distance between vertices

Alignment In The Cartesian Coordinate System

For precise and valid measurements of the vessel's geometry to be possible, the points of the scanned dataset must first and foremost be placed optimally in a Cartesian coordinate system. Several alignment methods and algorithms have been tested on a number of different vessels to determine the best way to achieve optimal alignment.

Any misalignment of the artifact will increase the error of the precision measurements, due to the distortion/wobble effect caused by the misaligned object. To visualize this distortion, we can consider a representation of the three-dimensional point cloud data, folded to a two-dimensional plane. This folded representation is obtained by rotating all scanned points around an assumed center axis to y = 0, x > 0, thus resulting in a two-dimensional profile representation of all scanned vertices in the object.

Figure 1 illustrates this effect on a ideal ellipsoid. In the first image, the ellipsoid is perfectly aligned, resulting in a narrow and precise two-dimensional folded profile. As misalignments are introduced, the two-dimensional profile increases in width, visually showing the distortion, causing the error in the precision measurements to increase. While easy to understand visually, this distortion can also be objectively quantified, and as such used to compare the fitness of different assumed center axes against each other, and further to create an automated and solid process for optimal Cartesian alignment of the scan data.

|			
Perfectly aligned ellipsoid	Ellipsoid translated 0.5mm (0.02 in) in both x and y coordinates	Ellipsoid rotated 0.5° in both x and y plane	Ellipsoid translated 0.5mm (0.02 in) in both x and y coordinates and rotated 0.5° in both x and y plane
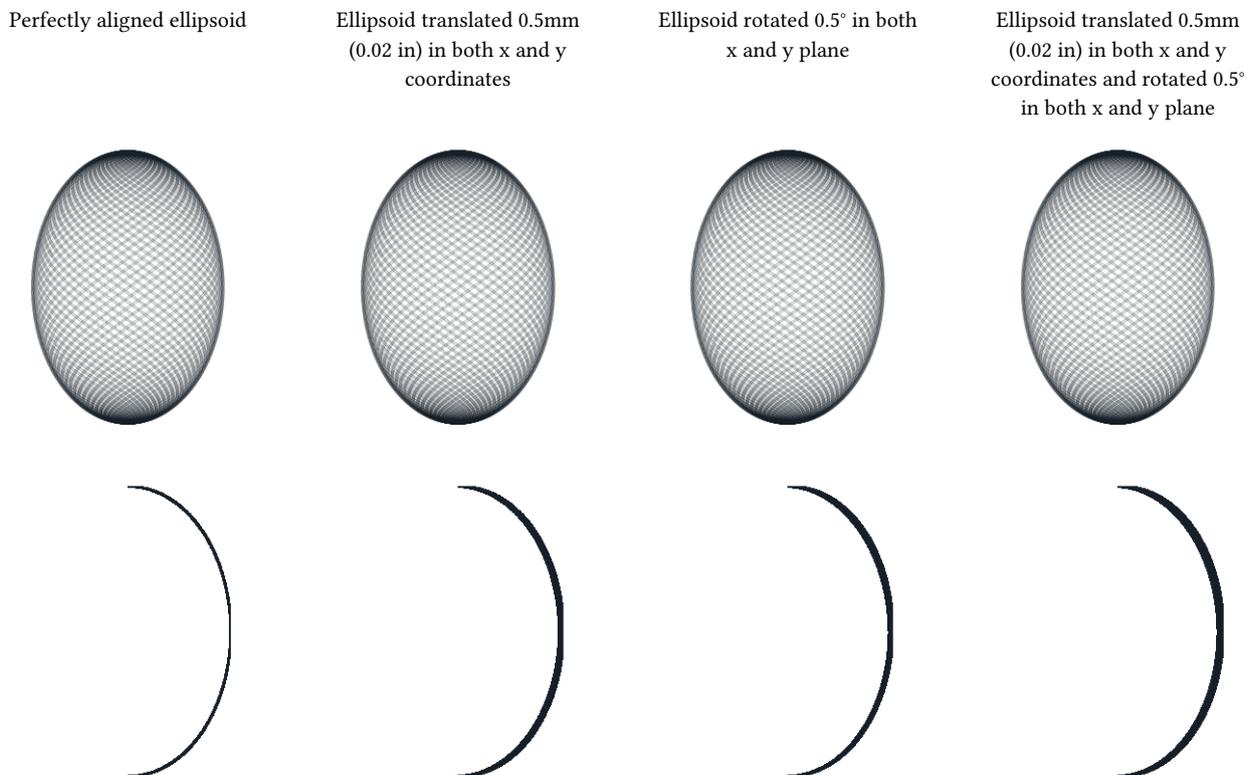
Figure 1: Distortion caused by a misalignment of the artifact

In contemporary metrology analysis of modern production objects, it is common to align the object in a Cartesian coordinate system by fitting a flat surface of the object to a reference plane in the coordinate system, cylindrical features to an ideal cylinder etc., or by using specific markers placed on the object in the design process. This methodology, however, is inadequate for the ancient objects in question. Most scanned artifacts, do not have a valid flat surface which could be aligned to a plane in the Cartesian coordinate system; most surfaces seem to be curved. Some artifacts do have a flat base, however this is often a worn area of the artifact and practical tests have shown that alignment to such surfaces will not produce optimal alignment of the scan data.

As conventional methods of alignment do not always yield good results with these types of artifacts, a more adequate method of alignment has been developed to enable precise measurements and statistical analysis of the scan data.

To find the optimal position of the vessel in the coordinate system, a range of rotation and translation tests are carried out to find the best fit of the central axis.

Based on the assumption that the analyzed object was created using a rotational process, and thus have symmetry around a central axis, the alignment of the artifact is carried out in a two-step process. An overview of this process is given below.

The artifact is placed in a Cartesian coordinate system, in an initially unaligned state. The first step in the alignment process estimates the central rotational axis of the vessel, by analyzing the coaxiality of thin cross-section slices of the vessel. The slices will be as thin as possible based on the mesh density of the scan, while still ensuring enough data points in each slice to be statistically valid.

For each slice, circular regression[7] (estimate of best fit circle) is used to estimate the center point of this slice. Combined over the total Z-axis range of the vessel, these center points provide us with an indicator of the incline and position of the vessel's central axis.

The next step will optimize the center axis alignment by progressively minimizing the deviation (perpendicular to the surface curvature) of the two-dimensional profile, see Figure 1. By ascertaining and comparing the resulting fit of many thousands of different potential rotations, the best fit alignment of the scan data can be estimated, and an optimal center axis (in relation to the data points) can be reconstructed. The actual three-dimensional point-cloud is then aligned to this axis, by rotating and translating the scanned data points to match the Z-axis of the Cartesian coordinate system.

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[7]Circle regression algorithm used: Kenichi Kanatani, Prasanna Rangarajan, "Hyper least squares fitting of circles and ellipses" Computational Statistics & Data Analysis, Vol. 55, pages 2197-2208, (2011)

Precision

To explore the manufacturing precision of the artifact in depth, the following analysis have been carried out:

- Circularity around the axis of symmetry is examined in detail at selected cross-sections.
- Overall circularity around the axis of symmetry is measured for the full height of the vessel (areas of the vessel with extensive damage are not taken into account for this metric).
- Concentricity of the vessel between selected cross-sections are examined in detail to determine if the existence of an axis of rotation in the manufacture of the object can be established.
- The coaxiality of the vessel is analyzed to explore the precision of the central axis of the object.
- The surface variability is analyzed and visualized on through a heatmap.

Circularity

Circularity is the measurement of how round the surface of an object is, optionally in reference to a datum axis. The *circularity tolerance* is the radial distance of two circles, each with their centers in the datum axis, and each of them conforming, respectively, to the minimum and maximum deviations of the data-set to a true circle, see Figure 2.
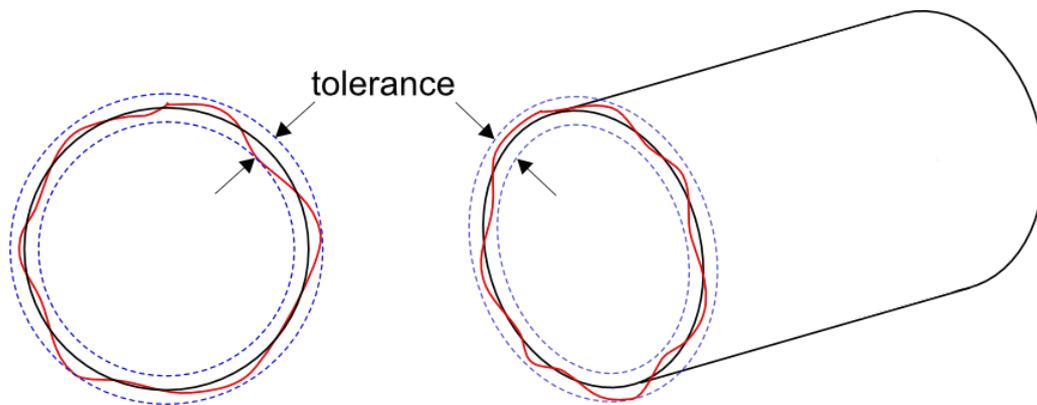

Figure 2: Circularity tolerance.

Circularity is examined at different cross-sections of the vessel, using the established Z-axis as the datum axis (axis of symmetry). The distance between the scanned points in the local datum plane is measured to determine the range between the two concentric circles encompassing the measured points, see Figure 3.

Referencing all of the individual circularity measurements to the global (reconstructed) axis of symmetry of the object, allows us to ascertain not only circularity of local features of the object, but how well circularity was *maintained* over the entire manufacturing process. This is an important distinction, which may be able to provide valuable insights into requirements of the construction methods. For reference, and seeing that the variance in local circularity also holds interest, measurements of circularity of the vessel without reference to the axis of symmetry can additionally be found in the Concentricity, p. 22.
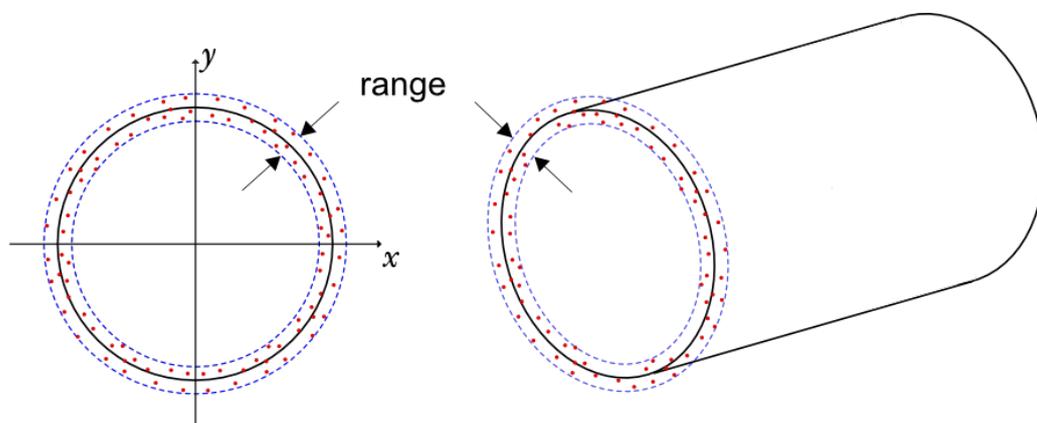
Figure 3: Circularity measurements.

If the circularity is determined from slices of the vessel exclusively in the *Z-plane* (actually measuring the cylindricity of a very thin slices of the vessel, in an attempt to approximate circularity), this would - in some areas - introduce significant distortion (increasing measurement errors) in the samples, due to the curvature of the vessel's surface.

Each sample slice of the vessel is therefore obtained perpendicular to the surface curvature, see Figure 5 to Figure 10. The measurements are taken conservatively without filtration of potential outliers.

To explore the potential distortion caused by obtaining samples in the Z-plane only, please refer to Appendix A, where measurements in the Z-plane and measurements perpendicular to surface curvature are compared side by side.

Detailed circularity measurements of selected points

Circularity measurements across a range of selected slices of the vessel (see Table 1) have been analyzed in-depth, and detailed plots of each measurement is provided. Furthermore, full circularity measurements are shown for each available scanned surface including a detailed plot to visualize the circularity of all areas of the vessel.
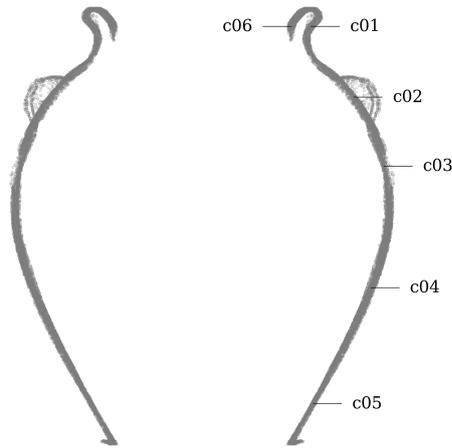
Figure 4: Circularity measurement sample location on MV001.

Metric

Tag	Area	Measured deviation[8]	Residuals				Sample size	Slice		
			Range	RMSD[9]	MAD[10]	SD		Height	Z coord.	Radius[11]
		mm	mm	mm	mm	mm		mm	mm	mm
c01	exterior	Ø84.210±2.044	3.565	0.793	0.645	0.788	2735	0.050	163.238	42.105
c02	exterior	Ø117.255±2.044	2.883	0.625	0.426	0.625	2557	0.050	135.782	58.628
c03	exterior	Ø140.569±2.373	3.235	0.631	0.439	0.630	2157	0.050	108.972	70.285
c04	exterior	Ø130.420±1.853	3.474	0.820	0.584	0.820	3575	0.050	61.781	65.210
c05	exterior	Ø85.775±0.920	1.724	0.397	0.327	0.397	2276	0.050	16.787	42.888
c06	interior	Ø69.001±1.587	2.953	0.739	0.666	0.735	3455	0.050	163.238	34.500

Imperial

Tag	Area	Measured deviation[8]	Residuals				Sample size	Slice		
			Range	RMSD[9]	MAD[10]	SD		Height	Z coord.	Radius[11]
		in	in	in	in	in		in	in	in
c01	exterior	Ø3.3153±0.0805	0.1404	0.0312	0.0254	0.0310	2735	0.0020	6.4267	1.6577
c02	exterior	Ø4.6163±0.0805	0.1135	0.0246	0.0168	0.0246	2557	0.0020	5.3457	2.3082
c03	exterior	Ø5.5342±0.0934	0.1274	0.0248	0.0173	0.0248	2157	0.0020	4.2902	2.7671
c04	exterior	Ø5.1346±0.0730	0.1368	0.0323	0.0230	0.0323	3575	0.0020	2.4323	2.5673
c05	exterior	Ø3.3770±0.0362	0.0679	0.0156	0.0129	0.0156	2276	0.0020	0.6609	1.6885
c06	interior	Ø2.7166±0.0625	0.1163	0.0291	0.0262	0.0289	3455	0.0020	6.4267	1.3583

Table 1: Detailed circularity measurements at selected samples of MV001.

Figure 5 to Figure 10 shows a detailed plots of each circularity measurement.

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[8] Sample diameter Ø± maximum measured deviation from measured radius

[9] Root mean square deviation (RMSD) also called Root mean square error (RMSE)

[10] Median absolute deviation

[11] Median sample radius from z-axis

Graphical overview of circularity measurement c01
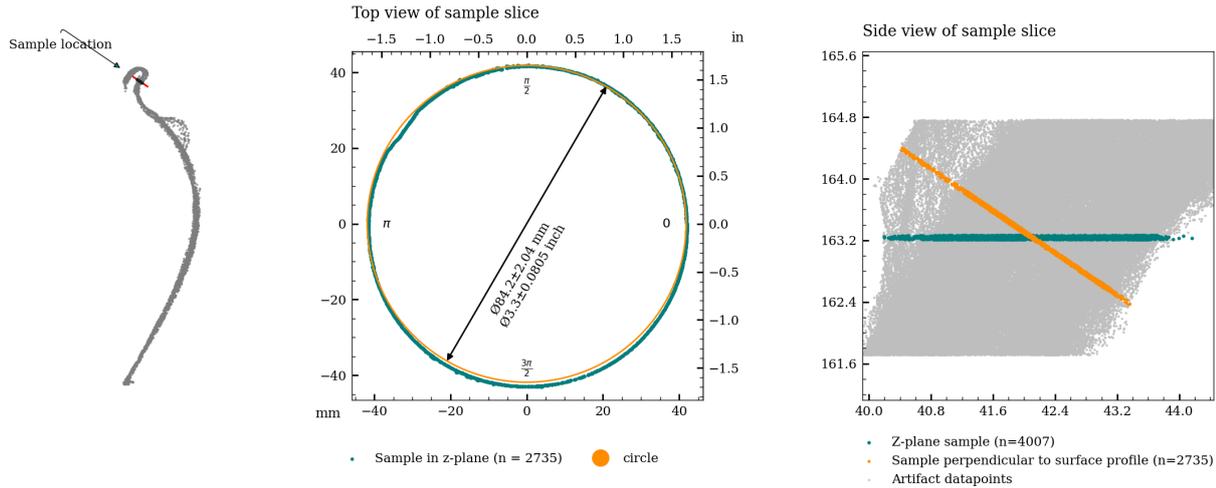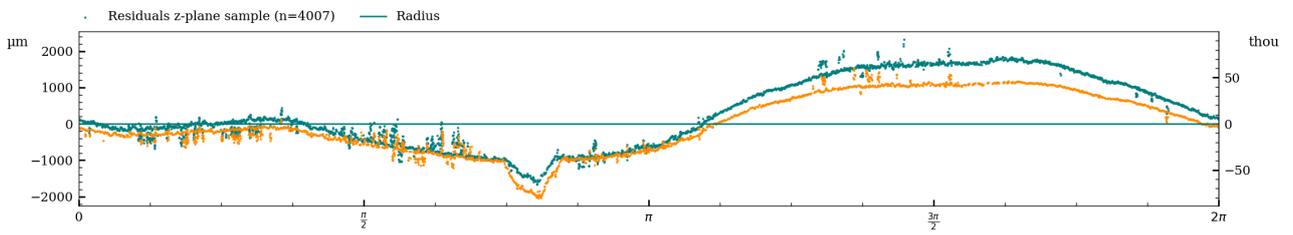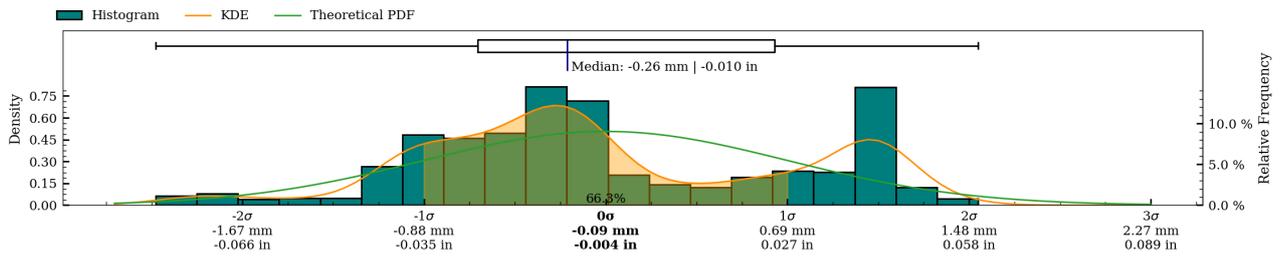
Figure 5: Charts with statistics for the measurement of c01.

Graphical overview of circularity measurement c02

Sample location

Top view of sample slice

Ø117.3±2.04 mm
Ø4.6±0.0805 inch

- Sample in z-plane (n = 2557)
- ● circle

Side view of sample slice

- Z-plane sample (n=4118)
- Sample perpendicular to surface profile (n=2557)
- Artifact datapoints

Residuals Plot - Circle circumference unwrapped to a line

- Residuals z-plane sample (n=4118)
- Radius

Histogram, PDF and Box-plot of Residuals perpendicular to surface tangent

- Histogram
- KDE
- Theoretical PDF

Median: 0.16 mm | 0.006 in

z-score outlier min

78.5%

	-3σ	-2σ	-1σ	0σ	1σ	2σ	3σ
	-1.86 mm	-1.23 mm	-0.61 mm	0.01 mm	0.64 mm	1.26 mm	1.89 mm
	-0.073 in	-0.049 in	-0.024 in	0.001 in	0.025 in	0.050 in	0.074 in

Figure 6: Charts with statistics for the measurement of c02.

Graphical overview of circularity measurement c03

Sample location

Top view of sample slice

Ø140.6±2.37 mm
Ø5.5±0.0934 inch

- Sample in z-plane (n = 2157)
- circle

Side view of sample slice

- Z-plane sample (n=2347)
- Sample perpendicular to surface profile (n=2157)
- Artifact datapoints

Residuals Plot - Circle circumference unwrapped to a line

- Residuals z-plane sample (n=2347)
- Radius

Histogram, PDF and Box-plot of Residuals perpendicular to surface tangent

- Histogram
- KDE
- Theoretical PDF

Median: -0.17 mm | -0.007 in

z-score outlier max

73.7%

|	-1σ	0σ	1σ	2σ	3σ	4σ
	-0.67 mm	-0.04 mm	0.59 mm	1.22 mm	1.85 mm	2.48 mm
	-0.026 in	-0.001 in	0.023 in	0.048 in	0.073 in	0.098 in

Figure 7: Charts with statistics for the measurement of c03.

Graphical overview of circularity measurement c04
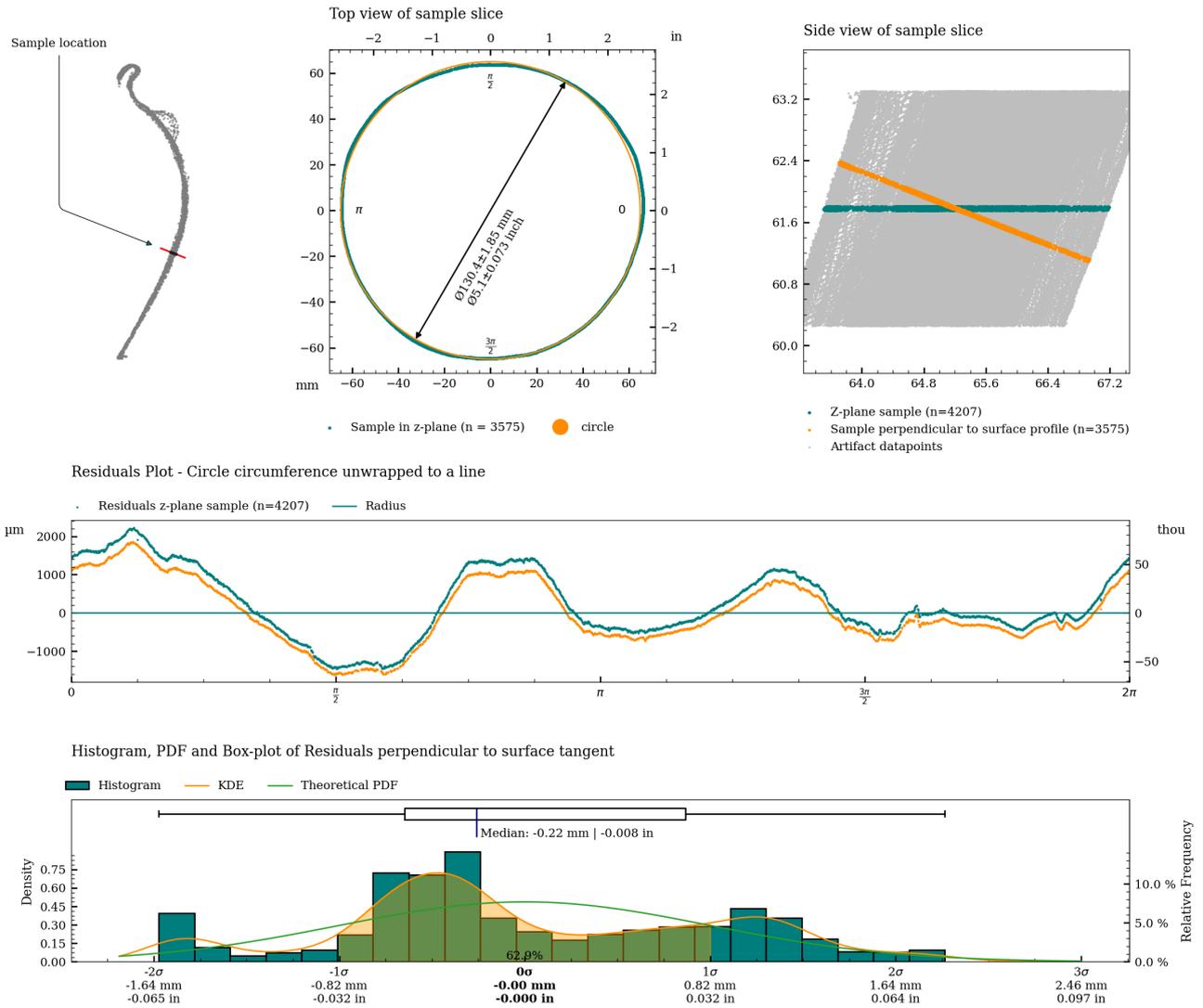
Figure 8: Charts with statistics for the measurement of c04.

Graphical overview of circularity measurement c05

Sample location

Top view of sample slice

Ø85.8±0.92 mm
Ø3.4±0.0362 inch

- Sample in z-plane (n = 2276)
- circle

Side view of sample slice

- Z-plane sample (n=3011)
- Sample perpendicular to surface profile (n=2276)
- Artifact datapoints

Residuals Plot - Circle circumference unwrapped to a line

- Residuals z-plane sample (n=3011)
- Radius

Histogram, PDF and Box-plot of Residuals perpendicular to surface tangent

- Histogram
- KDE
- Theoretical PDF

Median: -0.08 mm | -0.003 in

62.1%

-2σ	-1σ	0σ	1σ	2σ	3σ
-0.81 mm	-0.41 mm	**-0.01 mm**	0.38 mm	0.78 mm	1.18 mm
-0.032 in	-0.016 in	**-0.001 in**	0.015 in	0.031 in	0.046 in

Figure 9: Charts with statistics for the measurement of c05.

Graphical overview of circularity measurement c06

Top view of sample slice

Sample location

Ø69.0±1.59 mm
Ø2.7±0.0625 inch

- Sample in z-plane (n = 3455)
- ● circle

Side view of sample slice

- Z-plane sample (n=3715)
- Sample perpendicular to surface profile (n=3455)
- Artifact datapoints

Residuals Plot - Circle circumference unwrapped to a line

- Residuals z-plane sample (n=3715)
- — Radius

Histogram, PDF and Box-plot of Residuals perpendicular to surface tangent

- ■ Histogram
- — KDE
- — Theoretical PDF

Median: -0.18 mm | -0.007 in

55.9%

	-2σ	-1σ	0σ	1σ	2σ	3σ
	-1.55 mm	-0.81 mm	**-0.08 mm**	0.66 mm	1.39 mm	2.13 mm
	-0.061 in	-0.032 in	**-0.003 in**	0.026 in	0.055 in	0.084 in

Figure 10: Charts with statistics for the measurement of c06.

Table 2 shows statistical measures of the circularity of the vessel, measured along the full height (damaged parts may reduce the measurement area).

Metric

Area	Range			Standard Deviation			Medan Absolute Deviation			Slices	Slice height
	Median	Min.	Max.	Median	Min.	Max.	Median	Min.	Max.		
	mm	mm	mm	mm	mm	mm	mm	mm	mm		mm
Exterior	2.361	1.091	4.108	0.610	0.256	0.961	0.104	0.152	0.927	3243	0.050
Interior	2.366	1.584	3.152	0.668	0.468	0.762	0.090	0.367	0.677	100	0.050

Imperial

Area	Range			Standard Deviation			Medan Absolute Deviation			Slices	Slice height
	Median	Min.	Max.	Median	Min.	Max.	Median	Min.	Max.		
	in	in	in	in	in	in	in	in	in		in
Exterior	2.361	1.091	4.108	0.610	0.256	0.961	0.104	0.152	0.927	3243	0.050
Interior	2.366	1.584	3.152	0.668	0.468	0.762	0.090	0.367	0.677	100	0.050

Table 2: Perpendicular Circularity analysis of MV001.

Circularity analysis of exterior surface
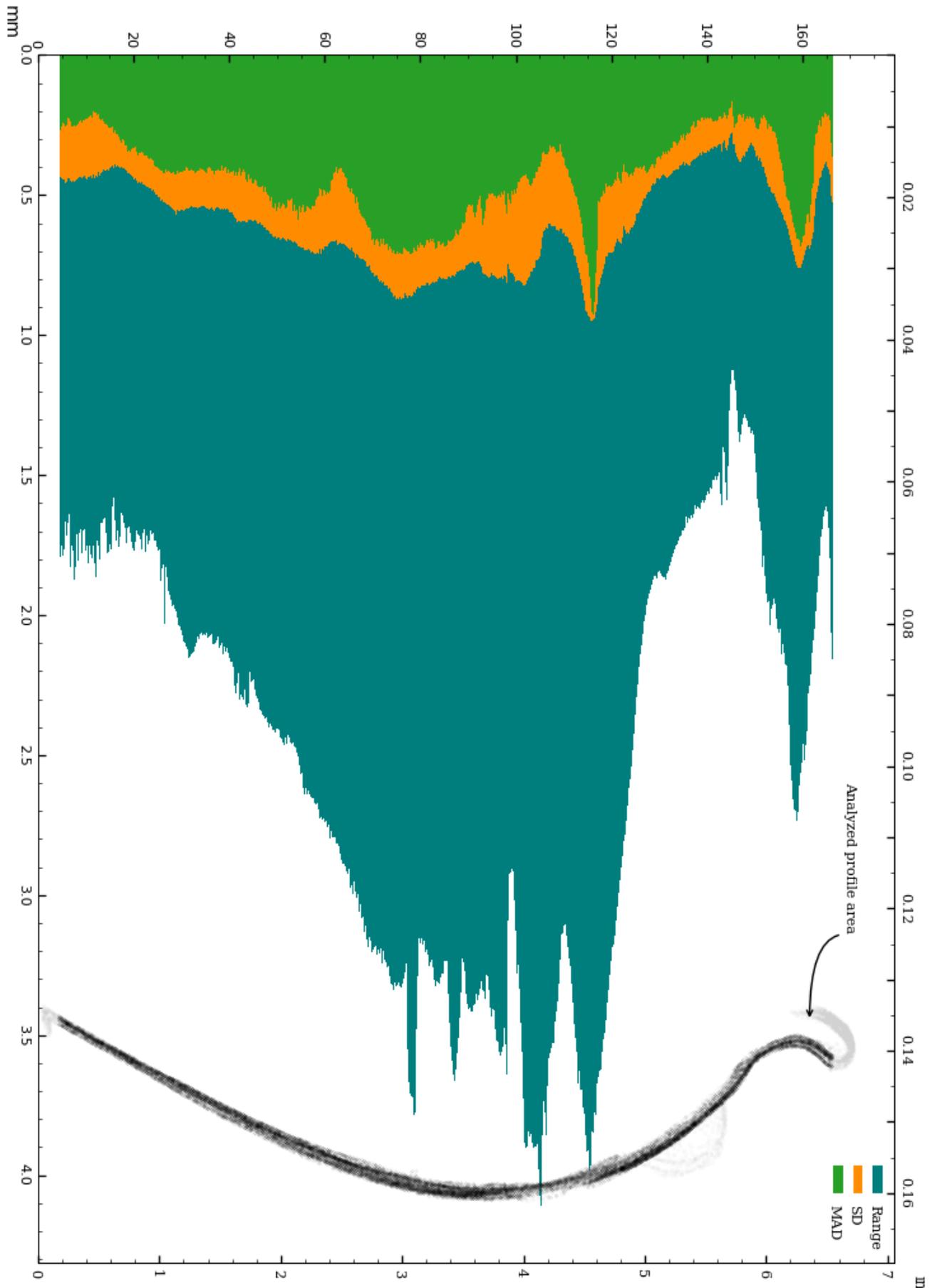
Figure 11: Circularity of exterior surface.

Circularity analysis of exterior surface, Standard Deviation and Median Absolute Deviation
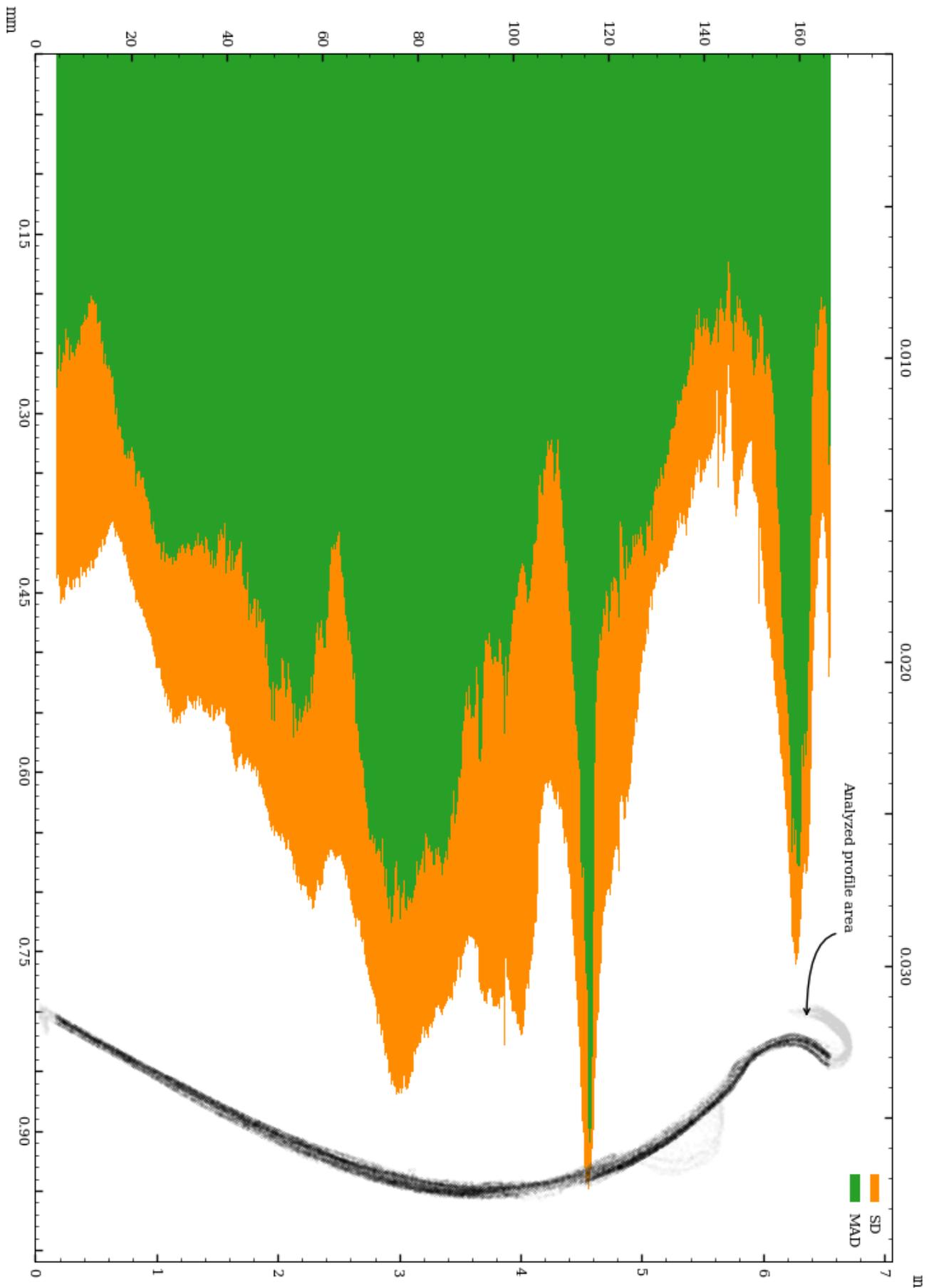

Figure 12: Vessel circularity of exterior surface, standard deviation and median absolute deviation.

The distributions of the circularity measurements across 3243 slices of the exterior surface are shown below.

**Range measurement distribution across 3243 slices of exterior surface**
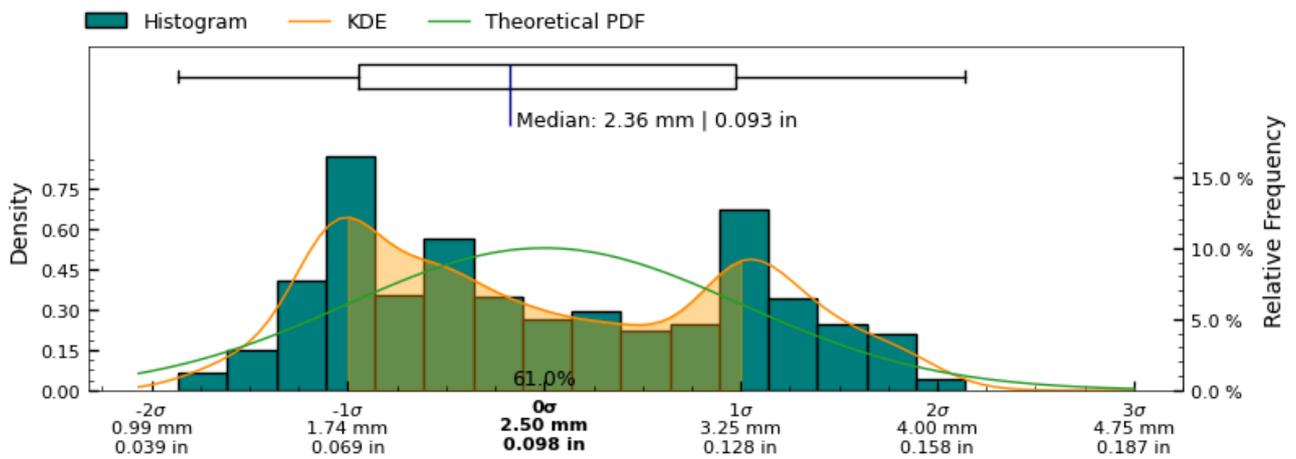
Figure 13: Range measurement distribution across measured slices of exterior surface

**Standard deviation measurement distribution across 3243 slices of exterior surface**
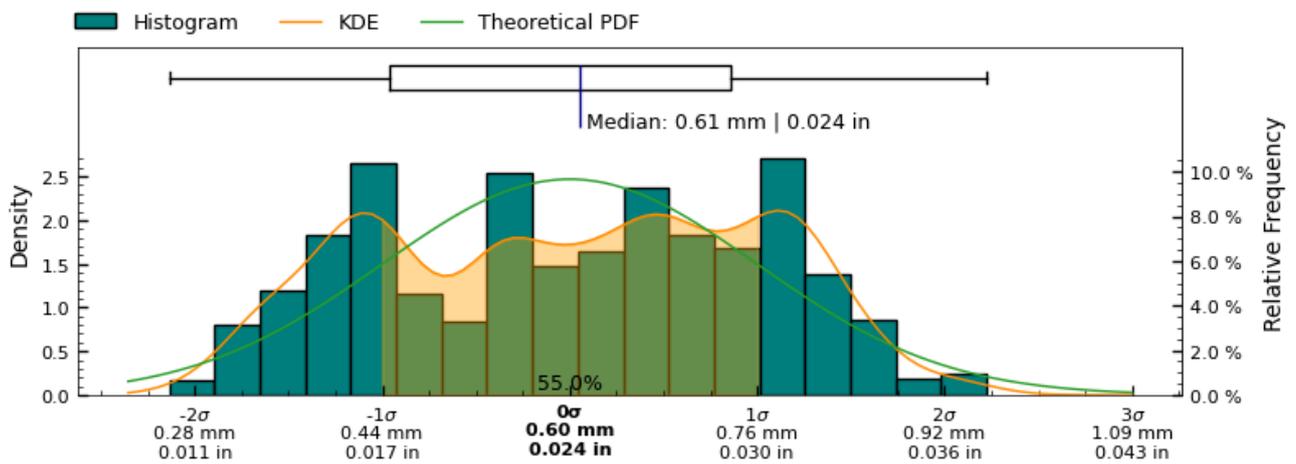
Figure 14: Standard deviation measurement distribution across measured slices of " + exterior + " surface

Median absolute deviation measurement distribution across 3243 slices of exterior surface
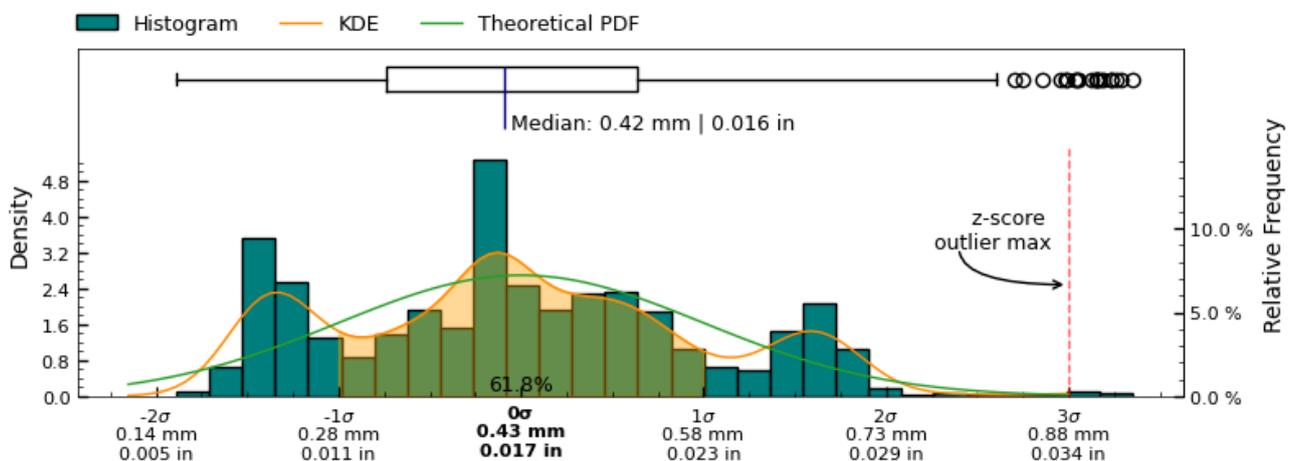
Figure 15: Median absolute deviation measurement distribution across measured slices of exterior surface

# Circularity analysis of interior surface
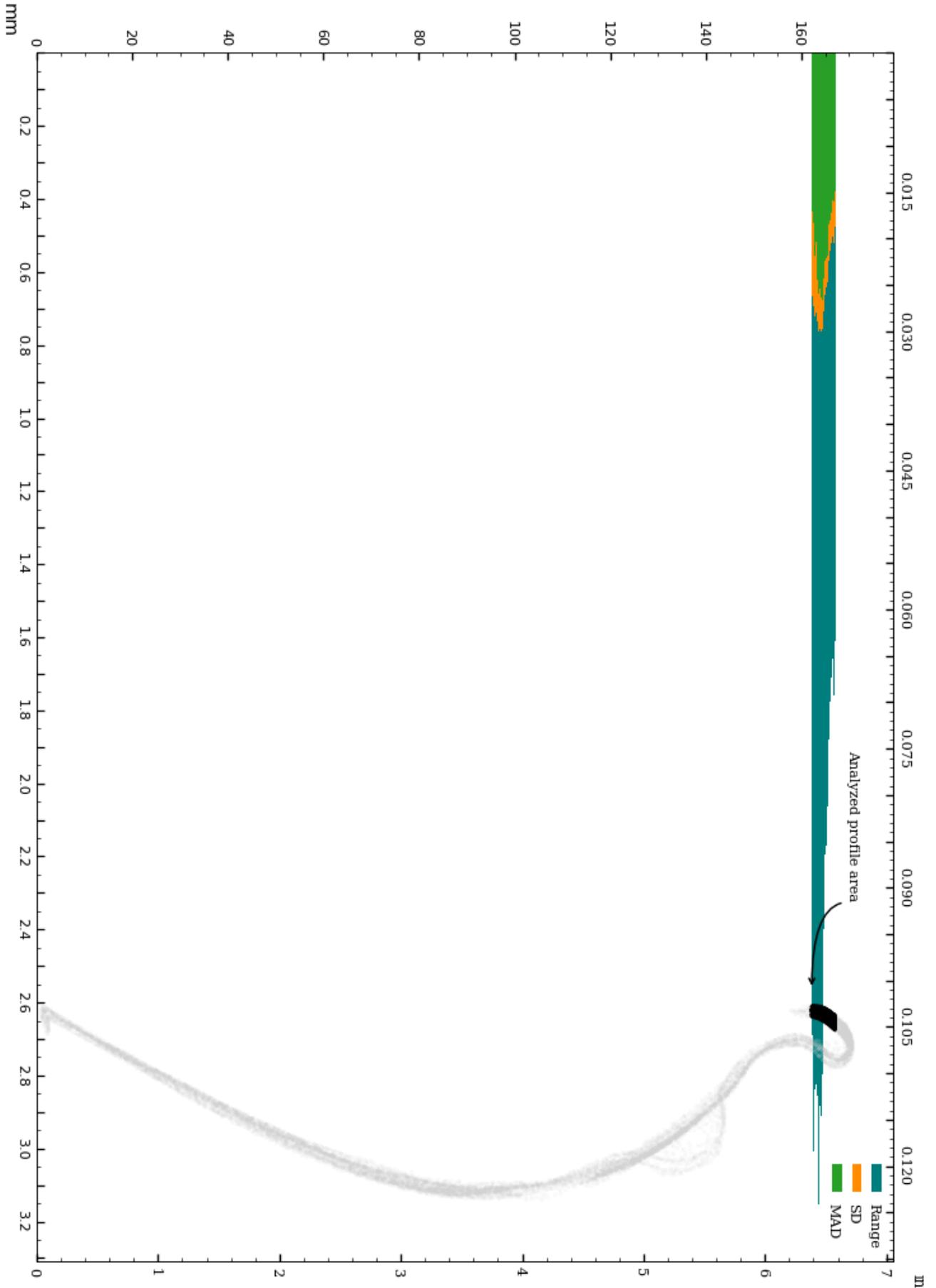
Figure 16: Circularity of interior surface.

Circularity analysis of interior surface, Standard Deviation and Median Absolute Deviation
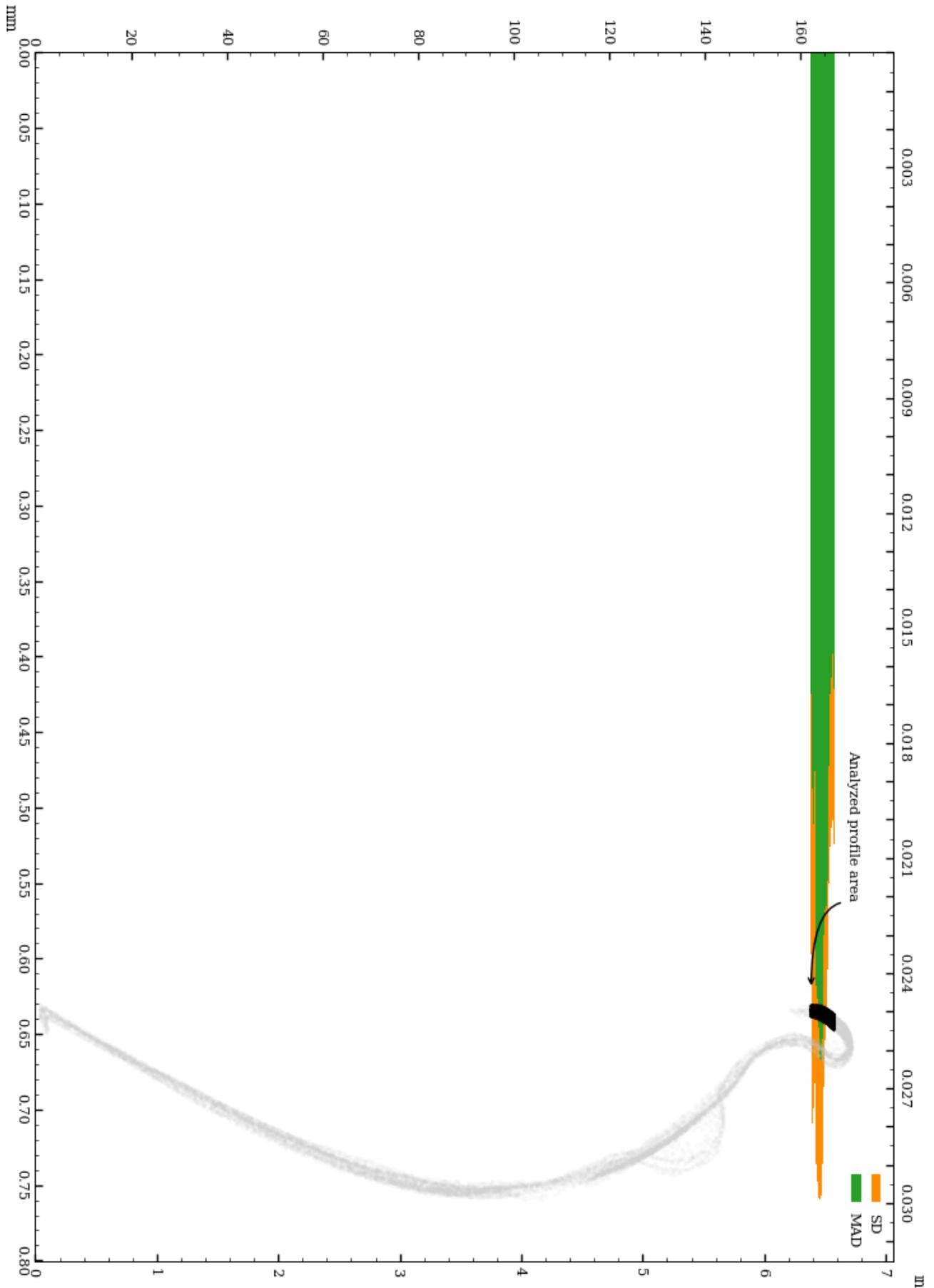

Figure 17: Vessel circularity of interior surface, standard deviation and median absolute deviation.

The distributions of the circularity measurements across 100 slices of the interior surface are shown below.

**Range measurement distribution across 100 slices of interior surface**
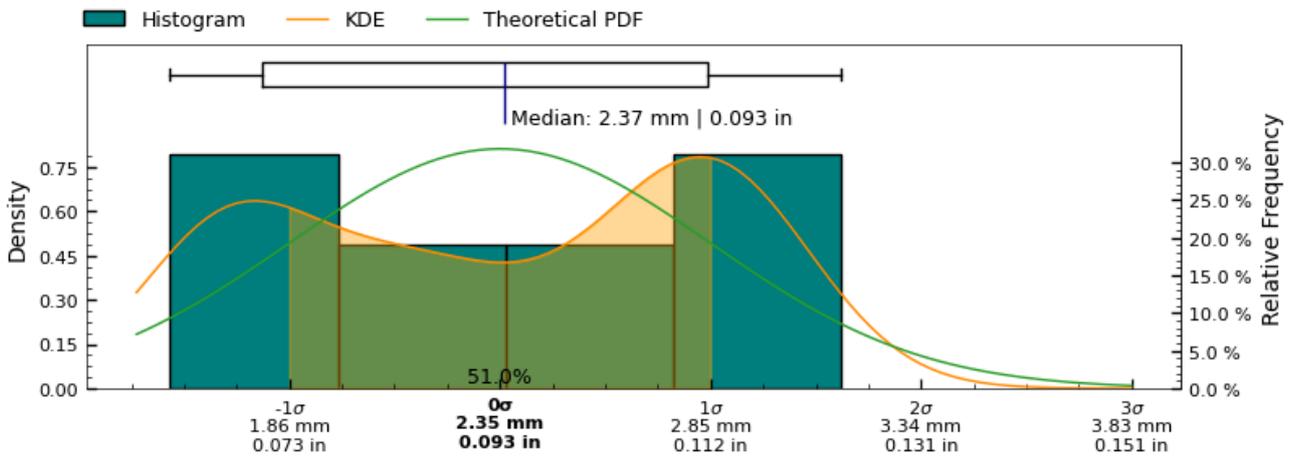
Figure 18: Range measurement distribution across measured slices of interior surface

Standard deviation measurement distribution across 100 slices of interior surface
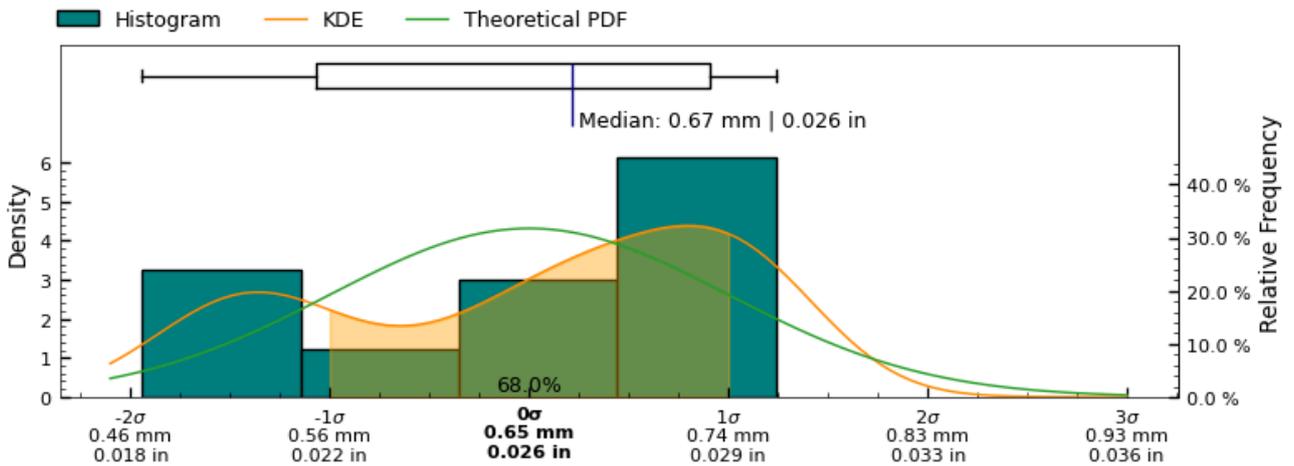

Figure 19: Standard deviation measurement distribution across measured slices of " + interior + " surface

**Median absolute deviation measurement distribution across 100 slices of interior surface**
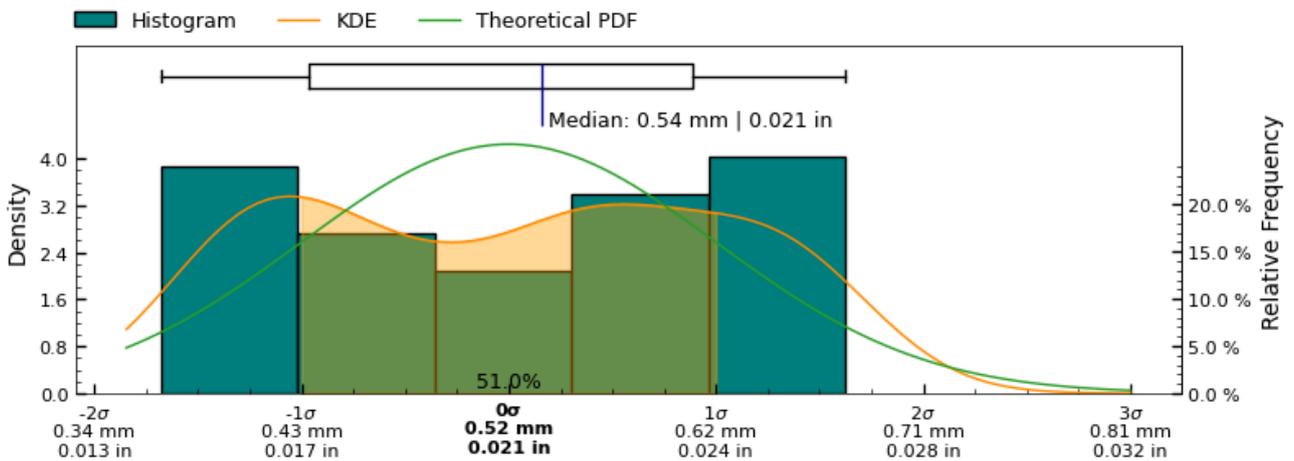
Figure 20: Median absolute deviation measurement distribution across measured slices of interior surface

Concentricity

The concentricity metric describes the deviation in the center-point of the referenced features. As such, it is a measure to determine if several features of the object share the same center point/axis, and how closely. See Figure 21 for a visual representation of this metric.
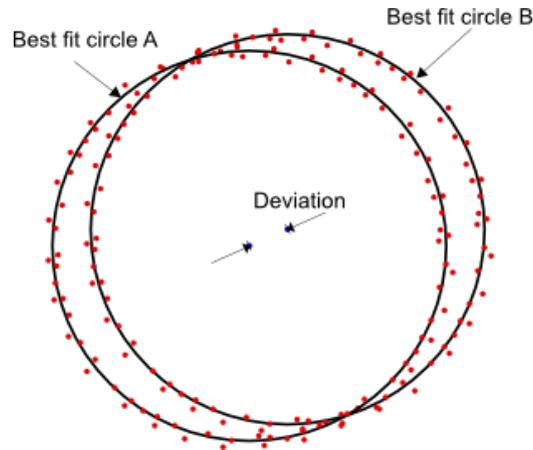

Figure 21: Concentricity measures the deviation (distance) between the center of two circles.

Determination of concentricity has been carried out by establishing the best fit circles of sample slices, using RANSAC (Random sample consensus) algorithm for outlier detection of a least squares circle regression on the scanned data-points at each cross-section, to estimate centers of each cross-section.

The concentricity between both the interior and exterior circular cross-sections is explored for cross-section measurements with the same Z-coordinates.

Additionally, the concentricity between each cross-section measurement defined in Figure 4 and the datum axis $(x, y) = (0, 0)$ has been calculated to establish the deviation of the feature center from the datum axis.
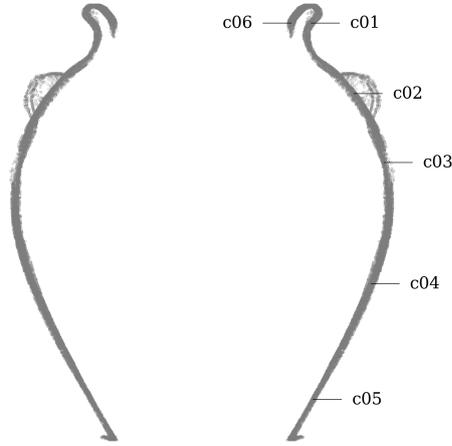
Figure 22: Concentricity measurement sample location on MV001.

Metric

Tag	Reference	Deviation	Sample size	Circle fit residuals analysis for sample listed in Tag column						
				Range full	Range inliers	SD full	SD inliers	MAD full	MAD inliers	Center (x,y)
		mm		mm	mm	mm	mm	mm	mm	µm
c01	z-axis	0.794	2735	3.565	3.361	0.788	0.758	0.526	0.518	280, −743
c02	z-axis	0.189	2557	2.883	2.122	0.625	0.498	0.334	0.310	−182, −52
c03	z-axis	0.205	2157	3.235	2.285	0.630	0.525	0.333	0.308	−149, 141
c04	z-axis	0.191	3575	3.474	3.474	0.820	0.820	0.486	0.486	190, −15
c05	z-axis	0.213	2276	1.724	1.724	0.397	0.397	0.292	0.292	−213, −16
c06	z-axis	0.900	3455	2.953	2.953	0.735	0.735	0.620	0.620	421, −796
c01	c06	0.150	2735	3.565	3.361	0.788	0.758	0.526	0.518	−141, 52

Imperial

Tag	Reference	Deviation	Sample size	Circle fit residuals analysis for sample listed in Tag column						
				Range full	Range inliers	SD full	SD inliers	MAD full	MAD inliers	Center (x,y)
		in		in	in	in	in	in	in	thou
c01	z-axis	0.0313	2735	0.1404	0.1323	0.0310	0.0298	0.0207	0.0204	11.0, −29.3
c02	z-axis	0.0074	2557	0.1135	0.0836	0.0246	0.0196	0.0131	0.0122	−7.1, −2.0
c03	z-axis	0.0081	2157	0.1274	0.0900	0.0248	0.0207	0.0131	0.0121	−5.9, 5.5
c04	z-axis	0.0075	3575	0.1368	0.1368	0.0323	0.0323	0.0191	0.0191	7.5, −0.6
c05	z-axis	0.0084	2276	0.0679	0.0679	0.0156	0.0156	0.0115	0.0115	−8.4, −0.6
c06	z-axis	0.0354	3455	0.1163	0.1163	0.0289	0.0289	0.0244	0.0244	16.6, −31.3
c01	c06	0.0059	2735	0.1404	0.1323	0.0310	0.0298	0.0207	0.0204	−5.5, 2.1

Table 3: Concentricity analysis of MV001.

Concentricity analysis of c01

Top view of sample slice with circle fit

r = 42.149 mm
1.65939 inch

center (x,y) = (280, -743) μm
(11.0, -29.3) thou

sample (n = 2735)   fitted circle

Side view of sample slice

Inlier Residuals (2690)
Outlier Residuals (45)
Artifact datapoints

Residuals Plot - Circle circumference unwrapped to a line

Inlier Residuals (2690)   Outlier Residuals (45)   radius

Histogram, PDF and Box-plot of Inlier Residuals

Histogram   KDE   Theoretical PDF

Median: -0.29 mm | -0.011 in

65.6%

	-2σ	-1σ	0σ	1σ	2σ	3σ
	-1.61 mm	-0.86 mm	-0.10 mm	0.66 mm	1.42 mm	2.17 mm
	-0.064 in	-0.034 in	-0.004 in	0.026 in	0.056 in	0.086 in

Figure 23: Detailed plot of concentricity measurement for c01.

Concentricity analysis of c02

Sample location

Top view of sample slice with circle fit

r = 58.746 mm
2.31284 inch

center (x,y) = (-182, -52) µm
(-7.1, -2.0) thou

- sample (n = 2557)
- fitted circle

Side view of sample slice

- Inlier Residuals (2402)
- × Outlier Residuals (155)
- Artifact datapoints

Residuals Plot - Circle circumference unwrapped to a line

- Inlier Residuals (2402)
- × Outlier Residuals (155)
- radius

Histogram, PDF and Box-plot of Inlier Residuals

- Histogram
- KDE
- Theoretical PDF

Median: 0.09 mm | 0.004 in

z-score outlier min

70.9%

-3σ	-2σ	-1σ	0σ	1σ	2σ	3σ
-1.47 mm	-0.97 mm	-0.48 mm	0.02 mm	0.52 mm	1.02 mm	1.51 mm
-0.058 in	-0.038 in	-0.019 in	0.001 in	0.020 in	0.040 in	0.060 in

Figure 24: Detailed plot of concentricity measurement for c02.

Concentricity analysis of c03

Top view of sample slice with circle fit

Sample location

r = 70.162 mm
2.76229 inch

center (x,y) =   (-149, 141) µm
(-5.9, 5.5) thou

- sample (n = 2157)
- fitted circle

Side view of sample slice

- Inlier Residuals (2079)
- Outlier Residuals (78)
- Artifact datapoints

Residuals Plot - Circle circumference unwrapped to a line

- Inlier Residuals (2079)
- Outlier Residuals (78)
- radius

Histogram, PDF and Box-plot of Inlier Residuals

- Histogram
- KDE
- Theoretical PDF

Median: -0.06 mm | -0.002 in

z-score
outlier max

69.4%

	-1σ	0σ	1σ	2σ	3σ
	-0.51 mm	0.01 mm	0.54 mm	1.06 mm	1.59 mm
	-0.020 in	0.001 in	0.021 in	0.042 in	0.063 in

Figure 25: Detailed plot of concentricity measurement for c03.

Concentricity analysis of c04

Sample location

Top view of sample slice with circle fit

r = 65.210 mm
2.56732 inch

center (x,y) =   (190, -15) µm
(7.5, -0.6) thou

- sample (n = 3575)   ● fitted circle

Side view of sample slice

- Inlier Residuals (3575)
- × Outlier Residuals (0)
- Artifact datapoints

Residuals Plot - Circle circumference unwrapped to a line

- Inlier Residuals (3575)   × Outlier Residuals (0)   — radius

Histogram, PDF and Box-plot of Inlier Residuals

- Histogram   — KDE   — Theoretical PDF

Median: -0.22 mm | -0.008 in

62.9%

	-2σ	-1σ	0σ	1σ	2σ	3σ
	-1.64 mm	-0.82 mm	-0.00 mm	0.82 mm	1.64 mm	2.46 mm
	-0.065 in	-0.032 in	-0.000 in	0.032 in	0.064 in	0.097 in

Figure 26: Detailed plot of concentricity measurement for c04.

Concentricity analysis of c05

Top view of sample slice with circle fit

r = 42.880 mm
1.68821 inch

center (x,y) =   (-213, -16) μm
(-8.4, -0.6) thou

Sample location

- sample (n = 2276)
- fitted circle

Side view of sample slice

- Inlier Residuals (2276)
- ✕ Outlier Residuals (0)
- Artifact datapoints

Residuals Plot - Circle circumference unwrapped to a line

- Inlier Residuals (2276) ✕ Outlier Residuals (0) — radius

Histogram, PDF and Box-plot of Inlier Residuals

- Histogram — KDE — Theoretical PDF

Median: -0.07 mm | -0.003 in

62.1%

	-2σ	-1σ	0σ	1σ	2σ	3σ
	-0.80 mm	-0.41 mm	**-0.01 mm**	0.39 mm	0.79 mm	1.18 mm
	-0.032 in	-0.016 in	**-0.000 in**	0.015 in	0.031 in	0.047 in

Figure 27: Detailed plot of concentricity measurement for c05.

Concentricity analysis of c06

Top view of sample slice with circle fit

Sample location

r = 34.508 mm
1.35858 inch

center (x,y) = (421, -796) µm
(16.6, -31.3) thou

- sample (n = 3455)
- fitted circle

Side view of sample slice

- Inlier Residuals (3455)
- × Outlier Residuals (0)
- Artifact datapoints

Residuals Plot - Circle circumference unwrapped to a line

- Inlier Residuals (3455)   × Outlier Residuals (0)   — radius

Histogram, PDF and Box-plot of Inlier Residuals

- Histogram   — KDE   — Theoretical PDF

Median: -0.19 mm | -0.008 in

55.9%

	-2σ	-1σ	0σ	1σ	2σ	3σ
	-1.56 mm	-0.82 mm	**-0.09 mm**	0.65 mm	1.38 mm	2.12 mm
	-0.061 in	-0.032 in	**-0.003 in**	0.026 in	0.054 in	0.083 in

Figure 28: Detailed plot of concentricity measurement for c06.

Coaxiality

Coaxiality is a measure of the deviation in the central axis of an object. Coaxiality measurements are calculated using RANSAC (Random sample consensus) algorithm for outlier detection of a least squares circle regression on cross-sections of the vessel (excluding potential handles) to estimate the best fit circle centers for each slice of the vessel.

Coaxiality is measured for:
- The exterior surface (excluding handles)
- The interior surface

	Exterior		Interior	
Analyzed Slices		3243		100
Median sample size		2693		4508
Slice Height	50 µm	2.0 thou	50 µm	2.0 thou
Statistics with Z-axis as Reference				
Median Absolute Deviation (MAD)	318 µm	12.5 thou	768 µm	30.3 thou
Standard Deviation (SD)	229 µm	9.0 thou	143 µm	5.6 thou
Root Mean Square Deviation (RMSD)	422 µm	16.6 thou	751 µm	29.6 thou
Statistics with Best Fit Central Axis as Reference				
Best fit Central Axis Equation (in metric coordinate system with unit [mm])	x = -0.093 + t0.00000 y = 0.171 + t-0.00077 z = 0.000 + t1.00000		x = 9.685 + t-0.05659 y = -11.319 + t0.06464 z = 0.000 + t0.99630	
Axis tilt		0°		−3.025°
Median Absolute Deviation (MAD)	283 µm	11.1 thou	69 µm	2.7 thou
Standard Deviation (SD)	199 µm	7.8 thou	42 µm	1.7 thou
Root Mean Square Deviation (RMSD)	399 µm	15.7 thou	87 µm	3.4 thou

Table 4: Coaxiality analysis of vessel MV001.

Coaxiality plots, exterior surface
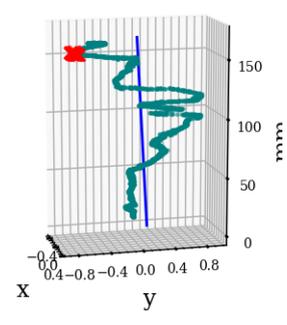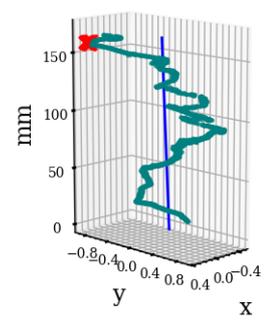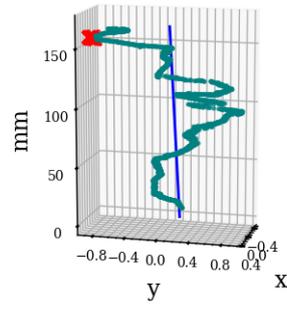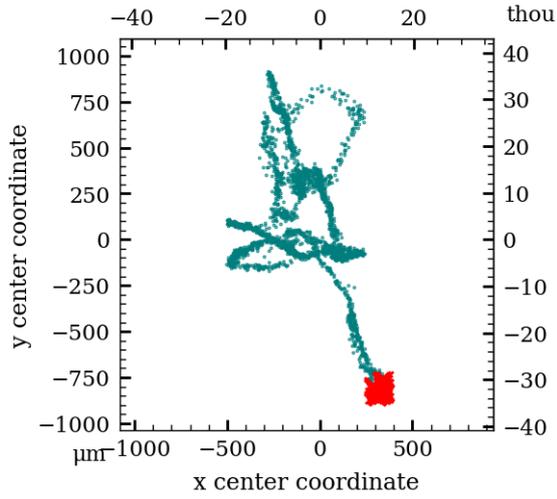
Coaxiality residuals from fitted axis, exterior surface
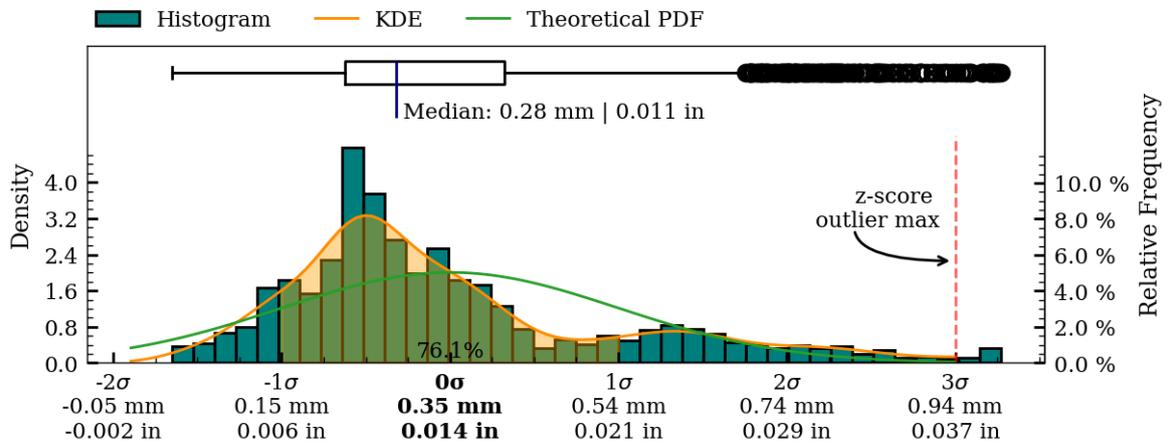
Figure 29: Coaxiality residual plots of exterior surface, MV001.

Coaxiality plots, interior surface
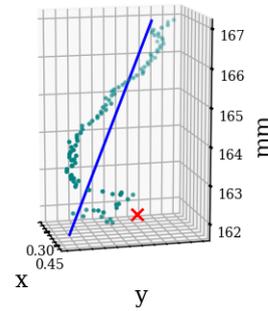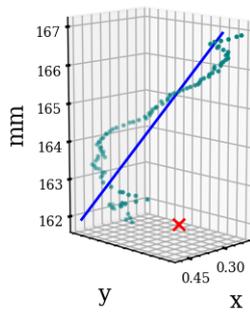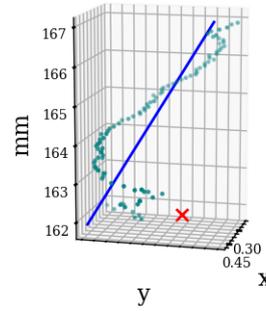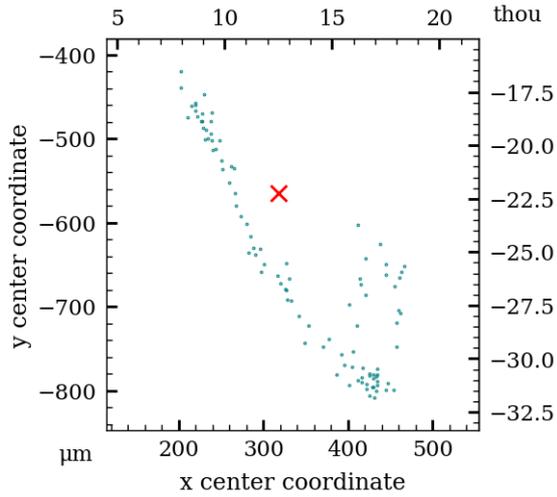
Coaxiality residuals from fitted axis, interior surface
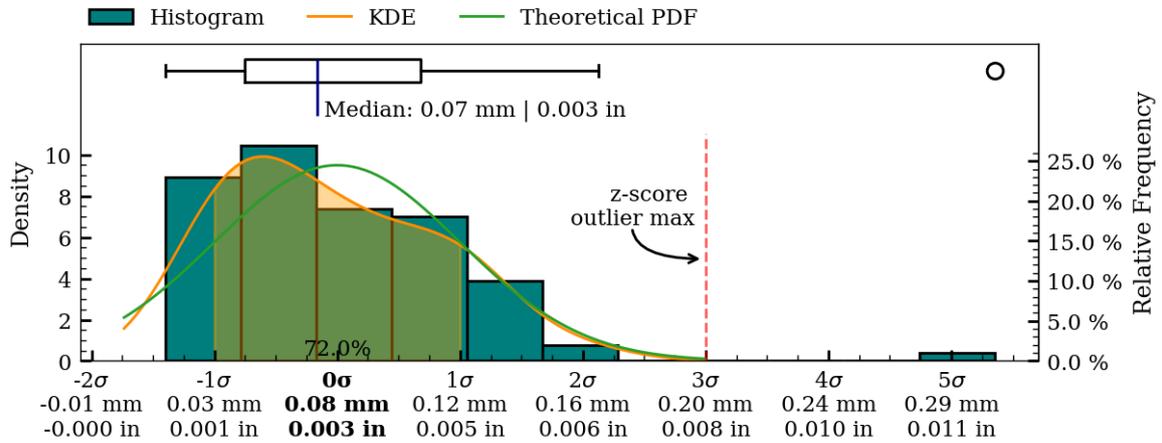
Figure 30: Coaxiality residual plots of interior surface, MV001.

Surface Variability

To illustrate the overall surface deviations of the object, a surface variability heatmap has been created. This heatmap provides an accessible overview of the topography of the manufacturing precision and surface structure of the object.

The surface variability measurements are created by fitting a number of higher-order polynomials to the two-dimensional folded profile of the scan data. This process creates an idealized mathematical representation of actual surface curvature of object, and as such provides a continuous model representation of the actual object. It is important to note that only such a non-discretized representation is sufficient to avoid introducing inconsistently varying errors in the mapping of the final surface deviation results, that the rendered heatmaps are based on.

To produce the final surface variability map, the distance from each scanned vertex to the fitted polynomial is calculated and used as the mapping function input, for applying colours to the surface of the object.

It is important to note that this variability map does not describe deviations from the original *intended* shape of the artifact (if any), as this shape (the *intended design*, so to speak) will have been lost to time. It does however provide a very informative visualization of the texture and structure of the surface and very importantly, *does* hightlight potential manufacturing-relevant patterns in the surface texture (if present). Such patterns are, as an example, clearly evident on the interior surface of artifact PV001.

Exterior surface
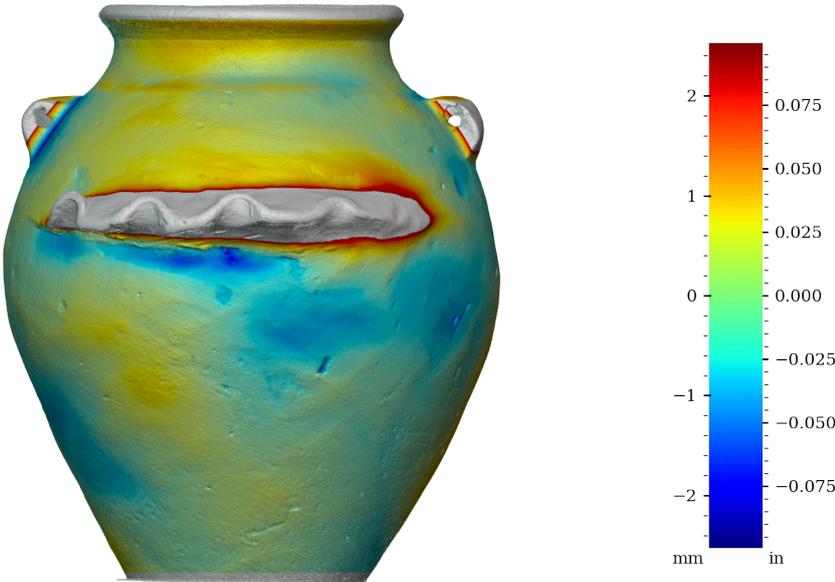
Figure 31: Surface variability heatmap of MV001, front view
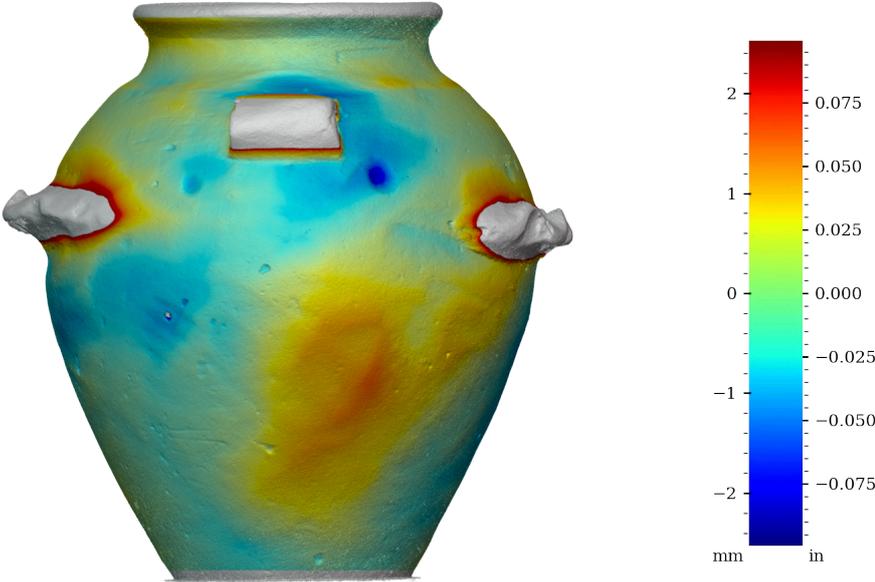
Figure 32: Surface variability heatmap of MV001, rotated 90°
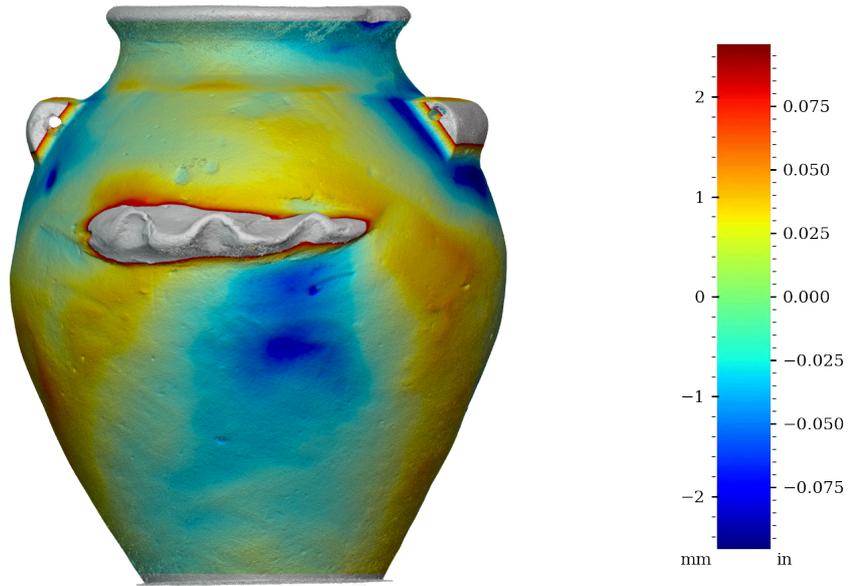
Figure 33: Surface variability heatmap of MV001, rotated 180°
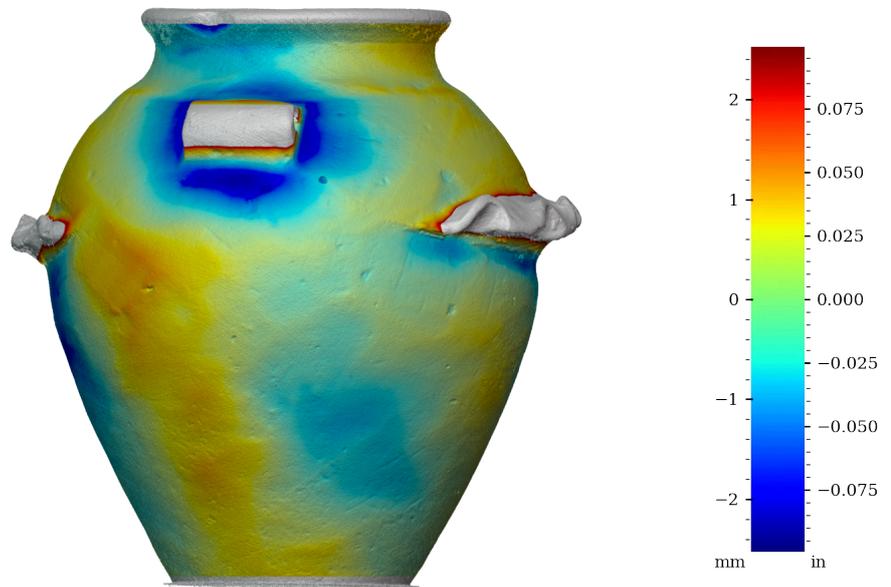
Figure 34: Surface variability heatmap of MV001, rotated 270°

Interior surface
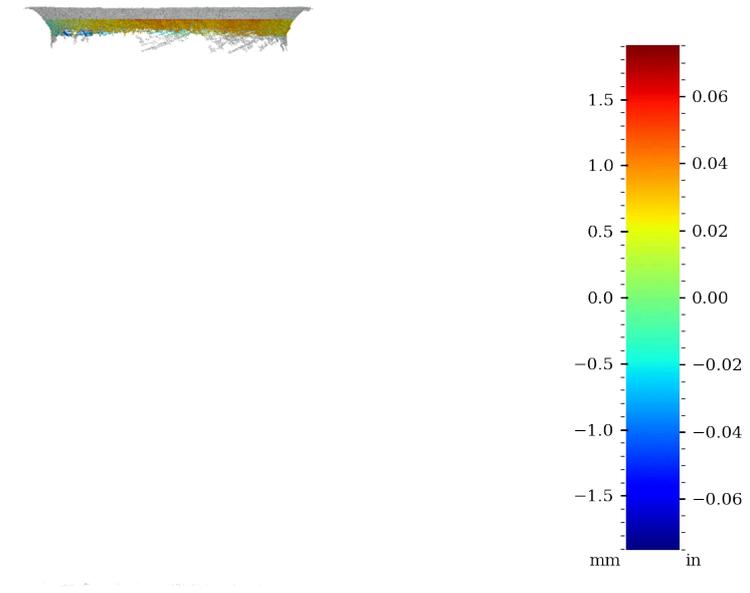
Figure 35: Surface variability heatmap of MV001, front view
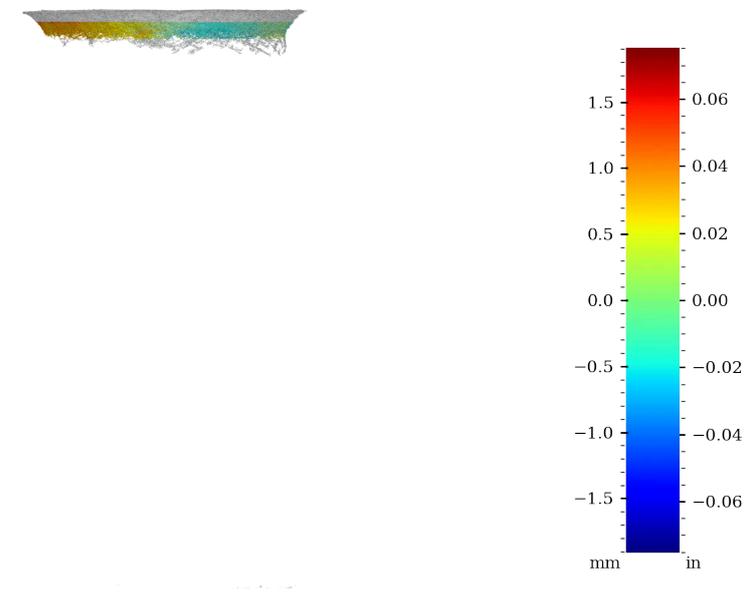
Figure 36: Surface variability heatmap of MV001, rotated 90°
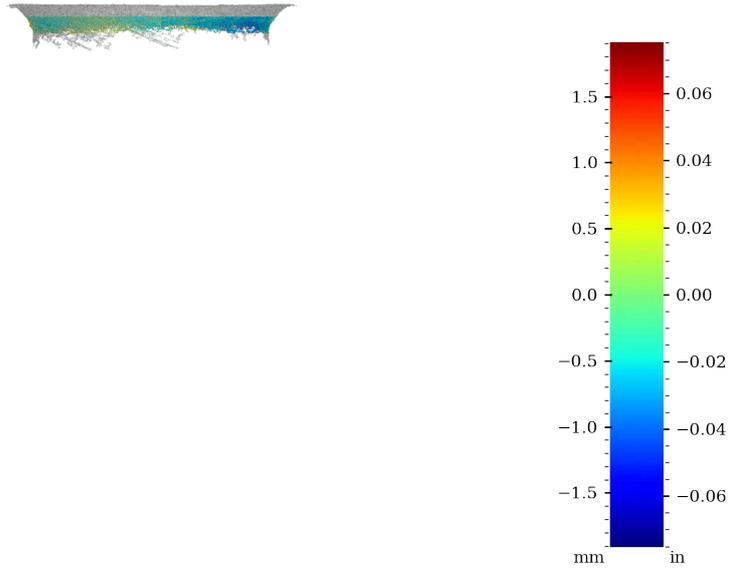
Figure 37: Surface variability heatmap of MV001, rotated 180°
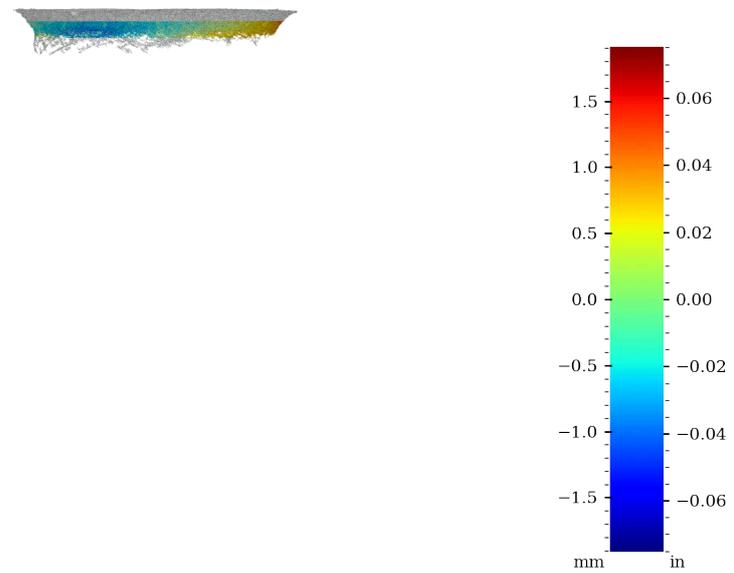
Figure 38: Surface variability heatmap of MV001, rotated 270°

Surface variability statistics

Area	MSD	RMSD	SD	Mean AD	Median AD	Range	Min	Max	Sample size
	mm²	mm	mm	mm	mm	mm	mm	mm	
Exterior	0.5195	0.721	0.721	0.507	0.582	6.565	−3.374	3.190	12132819
Interior	0.5405	0.735	0.735	0.658	0.647	3.610	−1.700	1.910	656834
	in²	in	in	in	in	in	in	in	
Exterior	0.000805	0.0284	0.0284	0.0200	0.0229	0.2584	−0.1328	0.1256	12132819
Interior	0.000838	0.0289	0.0289	0.0259	0.0255	0.1421	−0.0669	0.0752	656834

Table 5: Surface variability statistics, MV001

Table 5 shows the statistics of the distance from the scan vertices to the best fit object model. These statistics are briefly explained below.

Mean Squared Deviation (MSD), also known as Mean Squared Error (MSE).

$$\mathrm{MSD} = \frac{\sum_{i=1}^{n}(y_i - \hat{y})^2}{n}$$

The MSD metric shows the the average squared difference between the scanned points and the fitted composite polynomial model (a value of 0 would be a perfect match). This metric emphasizes imperfections in the surface of the artifact. Outliers will negatively influence this metric, raising the value of the MSE.

Root Mean Squared Deviation (RMSD), also known as Root Mean Squared Error (RMSE).

$$\mathrm{RMSD} = \sqrt{\frac{\sum_{i=1}^{n}(y_i - \hat{y})^2}{n}}$$

Measures the dispersion of the measured surface variability y_i around a model predictor ($\hat{y}$). By obtaining the root of the MSD, the exponent will be removed from the measurement, enabling comparisons with other statistics of the same unit and making it more accessible to those familiar with the RMSD metric. This measure is used to assess the fit of a regression model to a dataset, in this case our best fit composite polynomial model. The lower the RMSD metric, the better the fit.

Standard Deviation (SD)

$$s = \sqrt{\frac{\sum_{i=1}^{n}(y_i - \bar{y})^2}{n-1}}$$

Measures the dispersion of the measured surface variability y_i around the mean ($\bar{y}$). If the residuals are normally distributed around the mean ($\bar{y} \approx 0$), the SD will be equal to the RMSD. See Figure 39 and Figure 40

Mean Absolute Deviation (MeanAD)

$$\mathrm{MeanAD} = \frac{\sum_{i=1}^{n}|y_i - \bar{y}|}{n}$$

This metric is similar to the SD, but the difference between the residuals and the mean is *not* squared. Instead of indicating the spread of the data, we look at the average distance between each data point and the mean. The Mean Absolute Deviation is affected less by outliers than the Standard Deviation.

Median Absolute Deviation (MedianAD)

$$\mathrm{MedianAD} = \mathrm{median}(|y_i - \mathrm{median}(y)|)$$

The Median Absolute Deviation is measure of the dispersion of the data around the median.

Range

$$\max(y_i) - \min(y_i)$$

Range is a measure of the total spread of the residuals

Histogram, KDE and Box-plot of measured surface variability - exterior surface
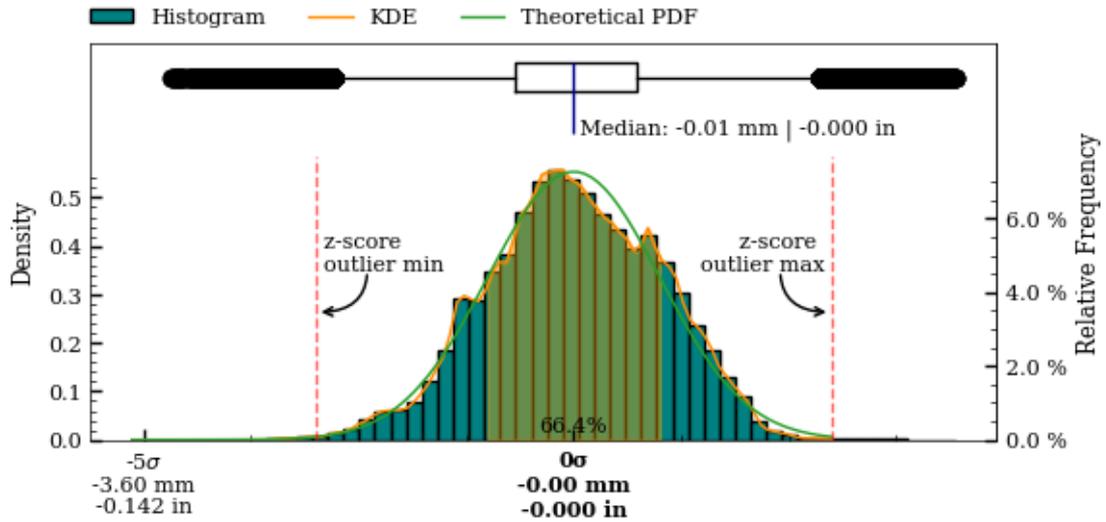

Figure 39: Exterior surface variability boxplot, kds and histogram.

**Histogram, KDE and Box-plot of measured surface variability - interior surface**
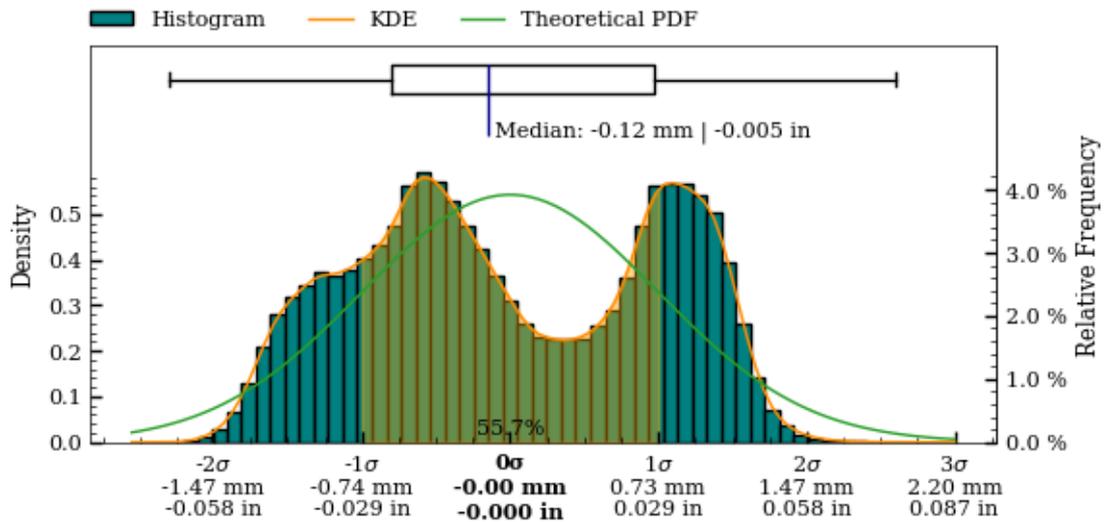
Figure 40: Interior surface variability boxplot, kds and histogram.

Precision Score Of The Artifact

To enable valid comparison of the manufacturing precision of different artifacts, a metric that robustly quantifies the overall precision of the object is required. The considerations for such a metric will be explored in this section.

Based on these considerations, a *Precision Score* metric will be defined.

For an object to be described as having been manufactured with high precision, several qualities must be present *concurrently*, and throughout the *entire* geometry of the final object. A given object may exhibit high levels of one or more *components* of precision, but be lacking in others. For example:

- An object may present high levels of coaxiality, but lack circularity.
- An object may exhibit good circularity, but show imperfections in the surface structure.
- An object may be smoothed to perfection *without* any circularity or coaxiality.
- An object may exhibit high levels of all of the above metrics in *some* areas, but not in others.

Therefore, a precision score metric **must** account for *all* aspects of the individual, underlying precision metrics (circularity, concentricity, coaxiality and surface variability) throughout the *entire* surface area of the object.

The composite high order polynomial model, used to generate the surface variability map (described in Surface Variability, p. 33) is the best continuous mathematical representation of the object available to us (lacking any original design plans, as would normally be available in metrological analysis). This idealized model encompasses all of the above component metrics.

In the creation of the model, all scan data-points are taken into account (excluding areas with extensive damage), making it the best possible idealized representation we can achieve. When this model has been accurately created, the deviation between the model and the scanned data-points can be calculated over the non-discretized polynomials, *without* the need for an "original" CAD model (and importantly, unless such a CAD model *actually* corresponded to the original design intent, it would be an insufficient comparison basis).

Within the context of defining a valid, overall precision metric, this approach satisfies the incorporation of all of the necessary metrics:

- **Circularity**: Because the reconstructed polynomial model is revolved around the Z-plane, the idealized representation is perfectly circular, and thus incorporates the circularity component.
- **Concentricity and coaxiality**: Because the Z-axis (datum axis) is the center axis of the model, it incorporates the concentricity and coaxiality components.
- **Surface variability**: Because the model is continuous and non-discretized, it can be used accurately for all points of the scan data, and incorporates the surface variability component.

The level of precision ultimately achieved in a physical object does not share a linear relationship with its manufacturing requirements. Since continuously higher levels of final precision becomes progressively harder to achieve, an overall precision metric must take this relationship into account.

A robust statistical metric that satisfies this requirement is the *Mean Squared Deviation* (MSD or MSE). Here specifically, we can utilize the mean square of the deviations between the model ($\hat{y}$) and the data-points (y_i).

Combining all of the above considerations, we can express a well-defined *Precision Score* metric, that provides an immediately accessible way to understand the overall precision of an object, while being statistically valid. Since the Mean Squared Deviation tends towards zero as the overall precision increases, the inverse of the Mean Squared Deviation is taken to obtain a precision score metric that increases as precision increases[12]:

$$\text{Precision Score} = \frac{n}{\sum_{i=1}^{n} (y_i - \hat{y})^2}$$

---

[12]The precision score unit is $\frac{1}{\text{mm}^2}$

A precision score will be calculated seperately for:

- The exterior surface
- The interior surface
- The full surface

As most scans do not include sufficient scan data for the interior surface, the exterior surface will be used for calculating the precision score in most cases. In the rare case that the scan data is more complete for the *interior* surface, this will be used instead.

Table 6 shows the precision score of this artifact (MV001), compared to the two most precise, and the two least precise vessels currently analyzed.

Artifact			Material	Precision Score	Link to Report
		PV001	Red Granite	**1905** Full: 980 Exterior: 1905 Interior: 705	Report Publication
		PV006	Dark grey granite	**621** Full: 521 Exterior: 621 Interior: 152	Report Publication
		MV001	Pottery	**1.93** Full: 1.92 Exterior: 1.93 Interior: 1.85	Report Publication
		MV010	Calcite (Egyptian Alabaster)	**1.12** Full: 0.64 Exterior: 1.12 Interior: 0.20	Report Publication (Draft - Awaiting publication)
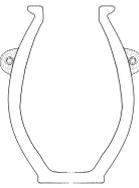
Analysis Roadmap

While the current iteration of this work already provides valuable results, continued future additions and improvements will enhance their utility further. This section details planned iterative updates and improvements, to both the reports themselves, and to the underlying methodology and software they are created with.

Alignment Section
- Detailed exploration of different circle regression algorithms
- If handles are present on the vessel, exploring alignment of the vessels so the handle positions match each other
- Add optimization of the perpendicular surface deviation, with the best results of the coaxial alignment
- Align by minimizing circularity results (of rotated sample slice, to compensate for sample height distortions)

Measurements of Precision
- Section detailing how measurements perpendicular to the surface curvature are obtained
- Detailed surface area analysis, exploring the residual patterns throughout subsequent sample slices of the artifact surface
- Wall thickness deviation color map
- Robust outlier identification on circularity, to better handle analysis of damaged areas of the artifacts in addition to removal of interior crystalline structure points present in CT scans
- Layout updates to the charts and tables

Visibility of Outliers and Damaged Sections
- Identification and marking of damaged parts
- Visualization of outliers on the artifact surface

Exploration of Mathematical Primitives
- Analysis of selected curvatures and flat surfaces on the vessel in both the horizontal and vertical planes
  - Circles
  - Parabolas
  - Ellipsoids
  - Hyperbolas
  - Cones
- Implementation of robust regressions models suitable for this domain, based on RANSAC.

Metrics on Primary Features
- Measurements of features in the horizontal plane
- Measurements of features in the vertical plane
- Measurements of angles
- Measurements of volume

**Exploration of Potential Design Ratios**
- π, φ, e, 1, 2, 3, 4 etc.

Raw Dataset Attachments
- Including all measurement and sample coordinates as CSV-files embedded in the report
- Including an STL file of the aligned object alongside the report, for easier external replication and validation of the research results

Appendix A - Comparison Of Circularity Measurements (Z-plane vs. surface-perpendicular)

Comparison of circularity samples

## Samples perpendicular to the surface curvature

Tag	Area	Measured deviation[8]	Residuals				Sample size	Slice			
			Range	RMSD[9]	MAD[10]	SD		Height	Z coord.	Radius[11]
		mm	mm	mm	mm	mm		mm	mm	mm
c01	exterior	Ø84.210±2.044	3.565	0.793	0.645	0.788	2735	0.050	163.238	42.105
c02	exterior	Ø117.255±2.044	2.883	0.625	0.426	0.625	2557	0.050	135.782	58.628
c03	exterior	Ø140.569±2.373	3.235	0.631	0.439	0.630	2157	0.050	108.972	70.285
c04	exterior	Ø130.420±1.853	3.474	0.820	0.584	0.820	3575	0.050	61.781	65.210
c05	exterior	Ø85.775±0.920	1.724	0.397	0.327	0.397	2276	0.050	16.787	42.888
c06	interior	Ø69.001±1.587	2.953	0.739	0.666	0.735	3455	0.050	163.238	34.500

Table 7: Detailed circularity measurements at selected samples in z-plane, vessel MV001.

Samples in the Z-plane

Tag	Area	Measured deviation[8]	Residuals				Sample size	Slice			
			Range	RMSD[9]	MAD[10]	SD		Height	Z coord.	Radius[11]
		mm	mm	mm	mm	mm		mm	mm	mm
c01	exterior	Ø83.704±2.313	3.970	0.967	0.668	0.931	4007	0.050	163.238	41.852
c02	exterior	Ø117.688±2.758	3.633	0.792	0.430	0.774	4118	0.050	135.782	58.844
c03	exterior	Ø140.208±2.761	3.469	0.653	0.322	0.640	2347	0.050	108.972	70.104
c04	exterior	Ø129.940±2.220	3.687	0.910	0.531	0.878	4207	0.050	61.781	64.970
c05	exterior	Ø85.602±1.105	1.815	0.462	0.337	0.455	3011	0.050	16.787	42.801
c06	interior	Ø68.794±1.579	3.094	0.774	0.726	0.769	3715	0.050	163.238	34.397

Table 8: Detailed circularity measurements at selected samples perpendicular to vessel curvature, vessel MV001.

Samples perpendicular to the surface curvature

Tag	Area	Measured deviation[8]	Residuals				Sample size	Slice		
			Range	RMSD[9]	MAD[10]	SD		Height	Z coord.	Radius[11]
		in	in	in	in	in		in	in	in
c01	exterior	Ø3.3153±0.0805	0.1404	0.0312	0.0254	0.0310	2735	0.0020	6.4267	1.6577
c02	exterior	Ø4.6163±0.0805	0.1135	0.0246	0.0168	0.0246	2557	0.0020	5.3457	2.3082
c03	exterior	Ø5.5342±0.0934	0.1274	0.0248	0.0173	0.0248	2157	0.0020	4.2902	2.7671
c04	exterior	Ø5.1346±0.0730	0.1368	0.0323	0.0230	0.0323	3575	0.0020	2.4323	2.5673
c05	exterior	Ø3.3770±0.0362	0.0679	0.0156	0.0129	0.0156	2276	0.0020	0.6609	1.6885
c06	interior	Ø2.7166±0.0625	0.1163	0.0291	0.0262	0.0289	3455	0.0020	6.4267	1.3583

Table 9: Detailed circularity measurements at selected samples in z-plane, vessel MV001.

Samples in the Z-plane

Tag	Area	Measured deviation[8]	Residuals				Sample size	Slice		
			Range	RMSD[9]	MAD[10]	SD		Height	Z coord.	Radius[11]
		in	in	in	in	in		in	in	in
c01	exterior	Ø3.2955±0.0910	0.1563	0.0381	0.0263	0.0366	4007	0.0020	6.4267	1.6477
c02	exterior	Ø4.6334±0.1086	0.1430	0.0312	0.0169	0.0305	4118	0.0020	5.3457	2.3167
c03	exterior	Ø5.5200±0.1087	0.1366	0.0257	0.0127	0.0252	2347	0.0020	4.2902	2.7600
c04	exterior	Ø5.1158±0.0874	0.1451	0.0358	0.0209	0.0346	4207	0.0020	2.4323	2.5579
c05	exterior	Ø3.3702±0.0435	0.0714	0.0182	0.0133	0.0179	3011	0.0020	0.6609	1.6851
c06	interior	Ø2.7084±0.0622	0.1218	0.0305	0.0286	0.0303	3715	0.0020	6.4267	1.3542

Table 10: Detailed circularity measurements at selected samples perpendicular to vessel curvature, vessel MV001.

Comparison of circularity on the full vessel surface

Metric

Samples perpendicular to the surface curvature

Area	Range			Standard Deviation			Medan Absolute Deviation			Slices	Slice height
	Median	Min.	Max.	Median	Min.	Max.	Median	Min.	Max.		
	mm	mm	mm	mm	mm	mm	mm	mm	mm		mm
Exterior	2.361	1.091	4.108	0.610	0.256	0.961	0.104	0.152	0.927	3243	0.050
Interior	2.366	1.584	3.152	0.668	0.468	0.762	0.090	0.367	0.677	100	0.050

Table 11: Detailed circularity measurements at selected samples in z-plane, vessel MV001.

Samples in the z-plane

Area	Range			Standard Deviation			Medan Absolute Deviation			Slices	Slice height
	Median	Min.	Max.	Median	Min.	Max.	Median	Min.	Max.		
	mm	mm	mm	mm	mm	mm	mm	mm	mm		mm
Exterior	3.345	1.804	5.847	0.767	0.444	1.428	0.109	0.226	1.002	3240	0.050
Interior	3.329	2.619	3.760	0.848	0.657	0.910	0.026	0.402	0.818	99	0.050

Table 12: Detailed circularity measurements at selected samples perpendicular to vessel curvature, vessel MV001.

Imperial

Samples perpendicular to the surface curvature

Area	Range			Standard Deviation			Medan Absolute Deviation			Slices	Slice height
	Median	Min.	Max.	Median	Min.	Max.	Median	Min.	Max.		
	in	in	in	in	in	in	in	in	in		in
Exterior	2.361	1.091	4.108	0.610	0.256	0.961	0.104	0.152	0.927	3243	0.050
Interior	2.366	1.584	3.152	0.668	0.468	0.762	0.090	0.367	0.677	100	0.050

Table 13: Detailed circularity measurements at selected samples in z-plane, vessel MV001.

Samples in the z-plane

Area	Range			Standard Deviation			Medan Absolute Deviation			Slices	Slice height
	Median	Min.	Max.	Median	Min.	Max.	Median	Min.	Max.		
	in	in	in	in	in	in	in	in	in		in
Exterior	3.345	1.804	5.847	0.767	0.444	1.428	0.109	0.226	1.002	3240	0.050
Interior	3.329	2.619	3.760	0.848	0.657	0.910	0.026	0.402	0.818	99	0.050

Table 14: Detailed circularity measurements at selected samples perpendicular to vessel curvature, vessel MV001.

## Circularity analysis of exterior samples perpendicular to surface curvature
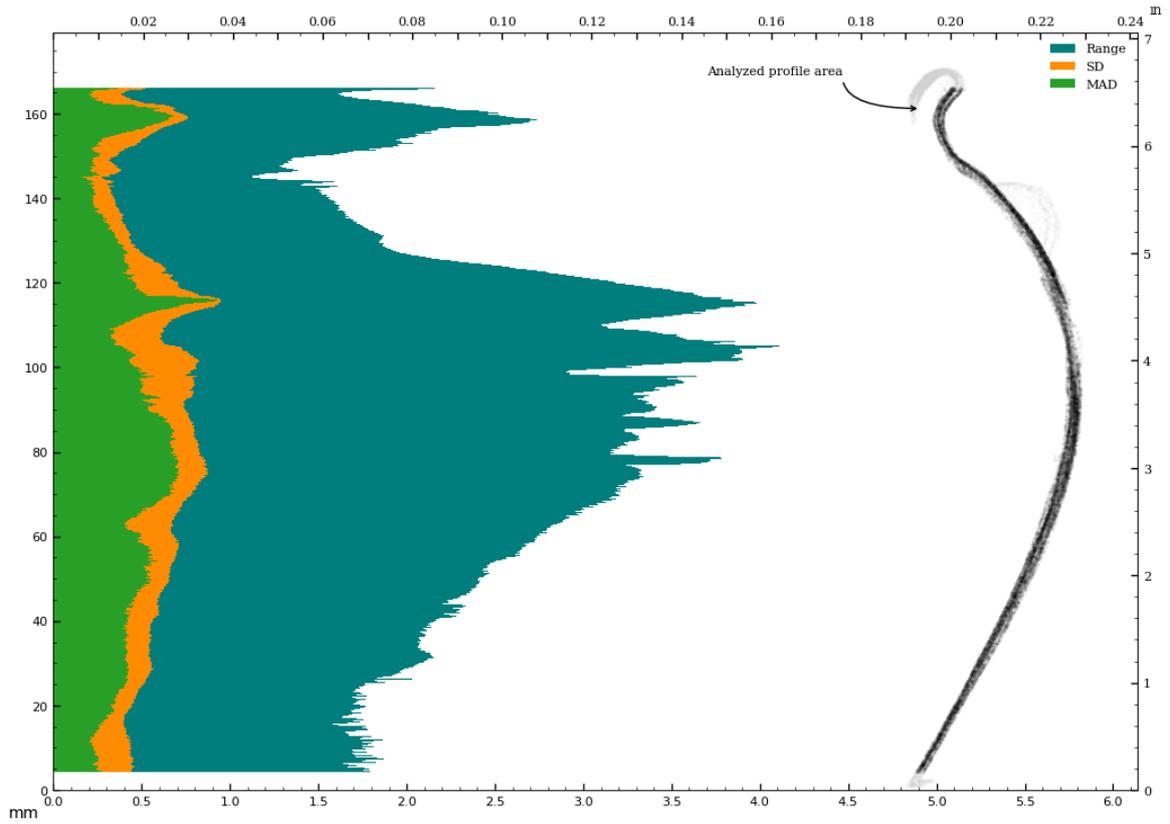
Figure 41: Circularity analysis of exterior samples perpendicular to surface curvature

Circularity analysis of exterior surface - in z-plane
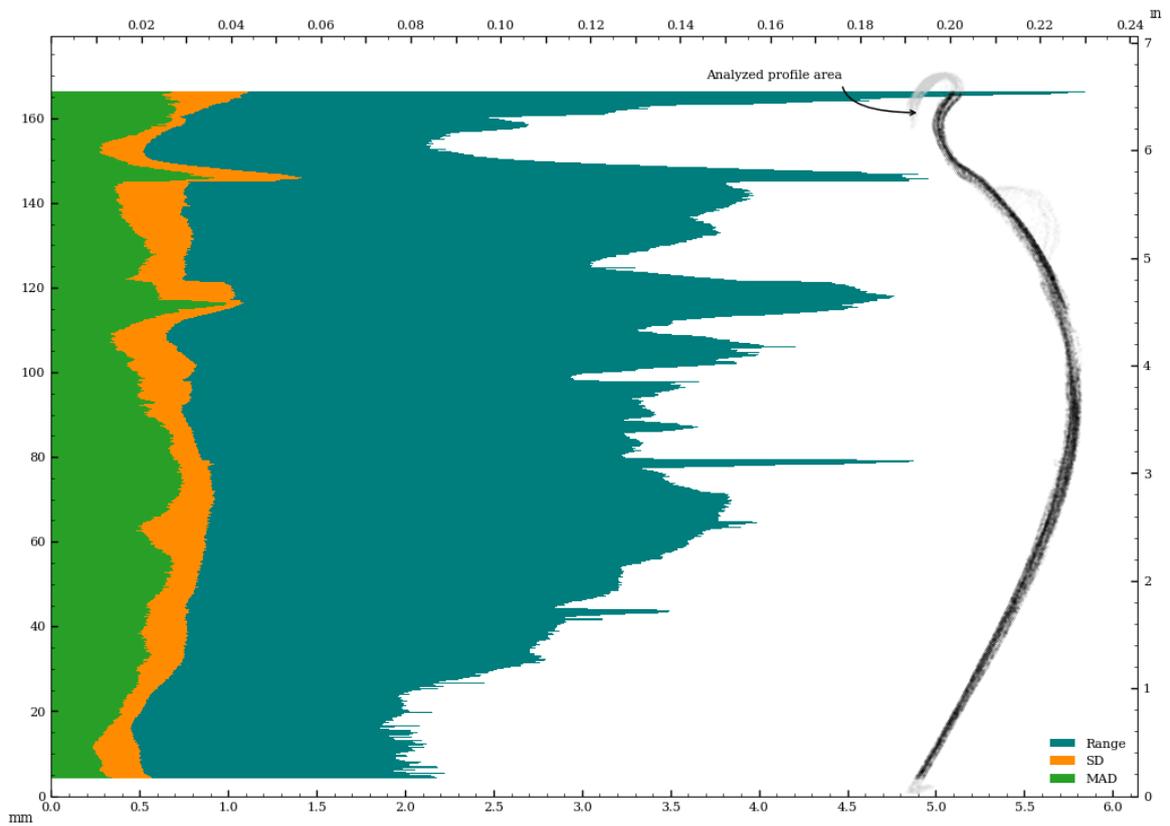

Figure 42: Circularity analysis of exterior surface - in z-plane

Circularity analysis of exterior samples perpendicular to surface curvature
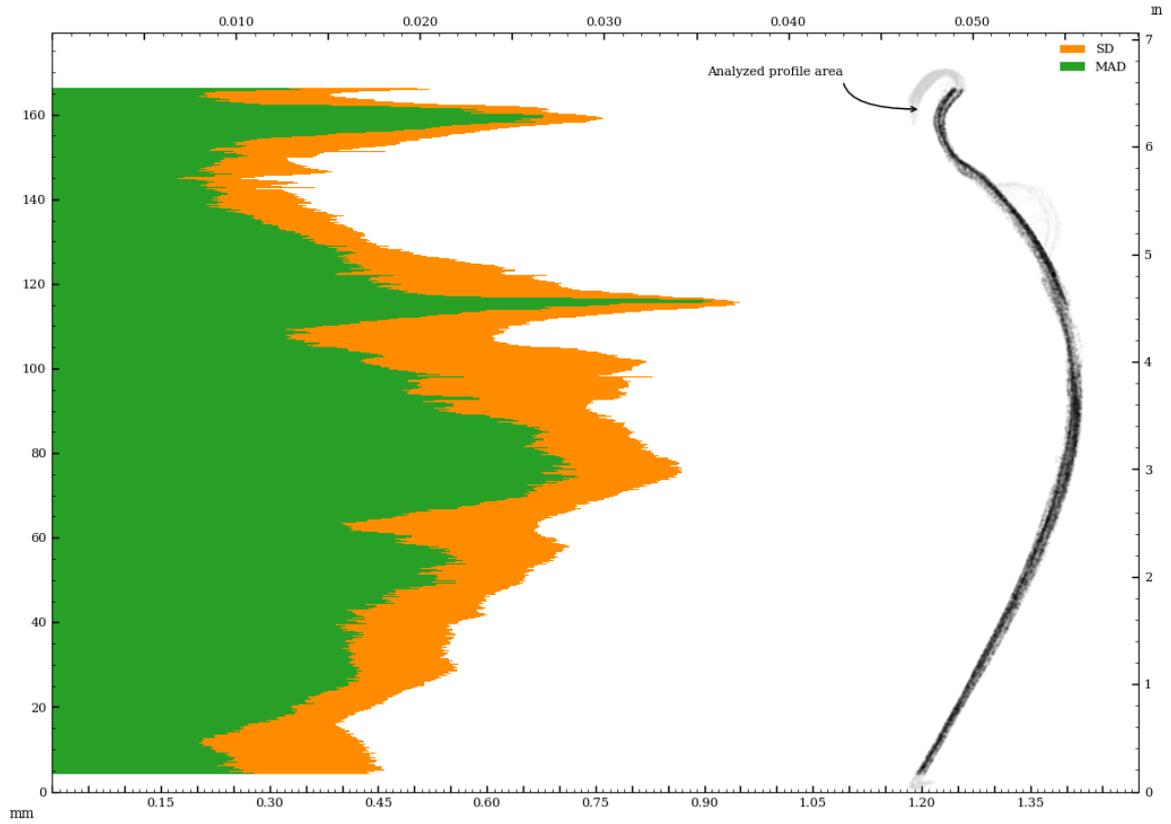
Figure 43: Circularity analysis of exterior samples perpendicular to surface curvature

Circularity analysis of exterior surface - in z-plane
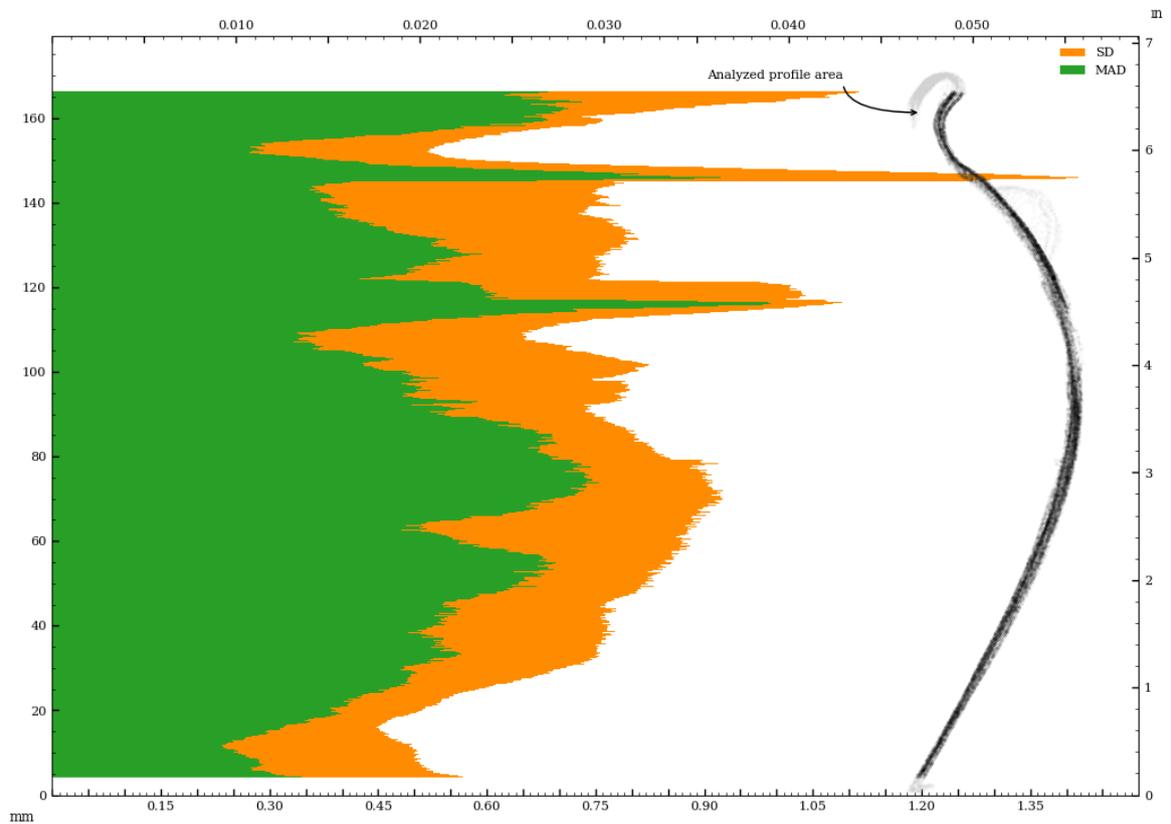
Figure 44: Circularity analysis of exterior surface - in z-plane

## Circularity analysis of interior samples perpendicular to surface curvature
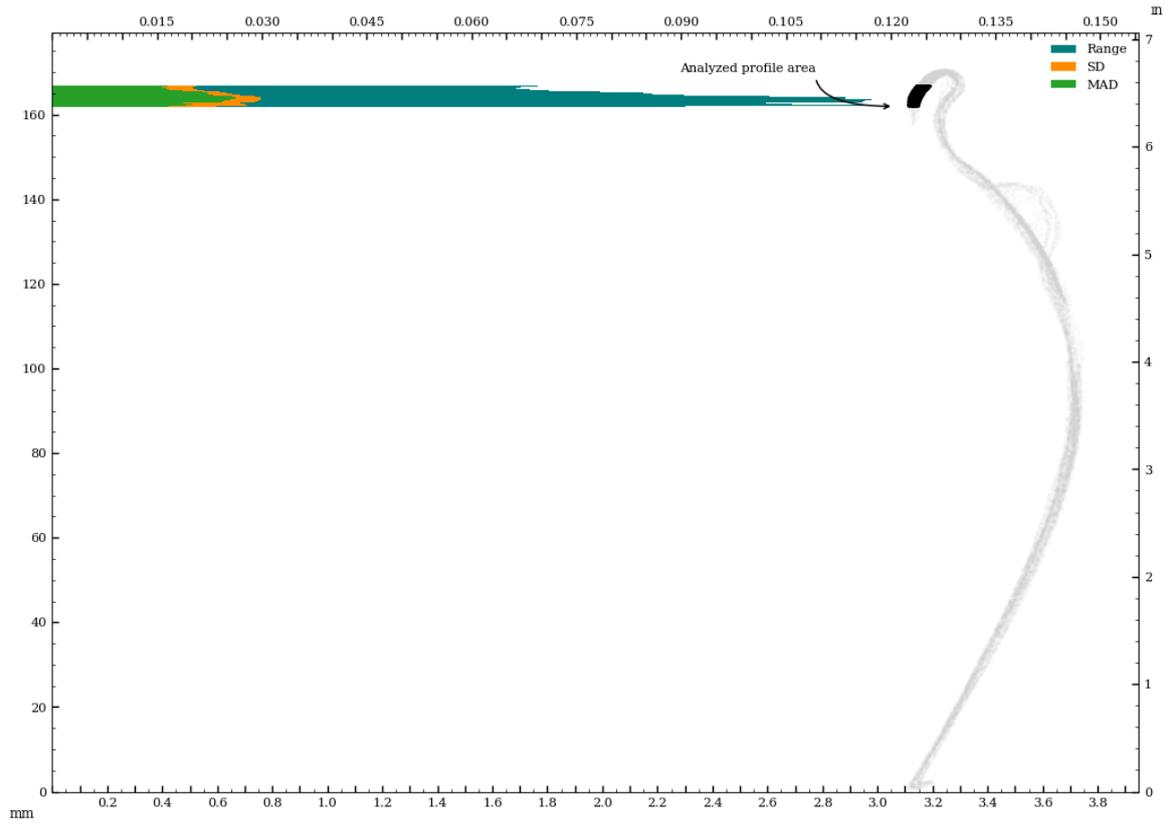
Figure 45: Circularity analysis of interior samples perpendicular to surface curvature

Circularity analysis of interior surface - in z-plane
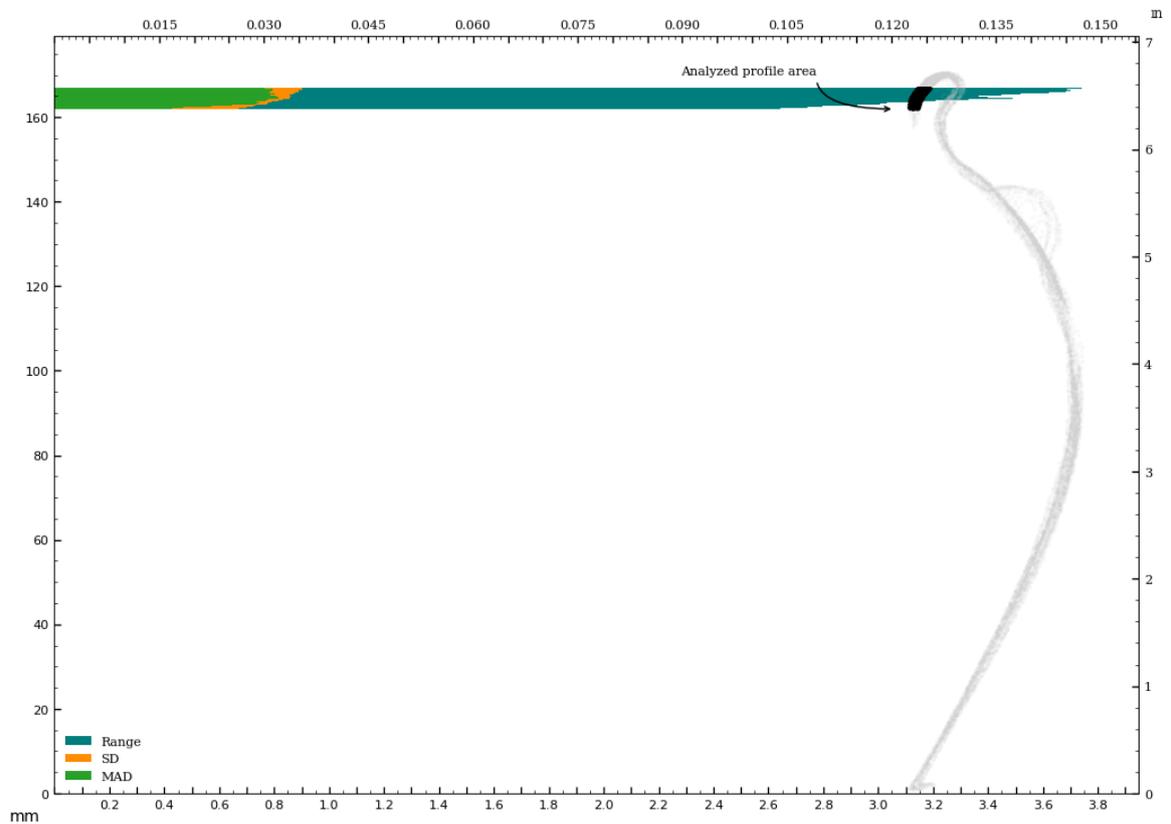

Figure 46: Circularity analysis of interior surface - in z-plane

Circularity analysis of interior samples perpendicular to surface curvature
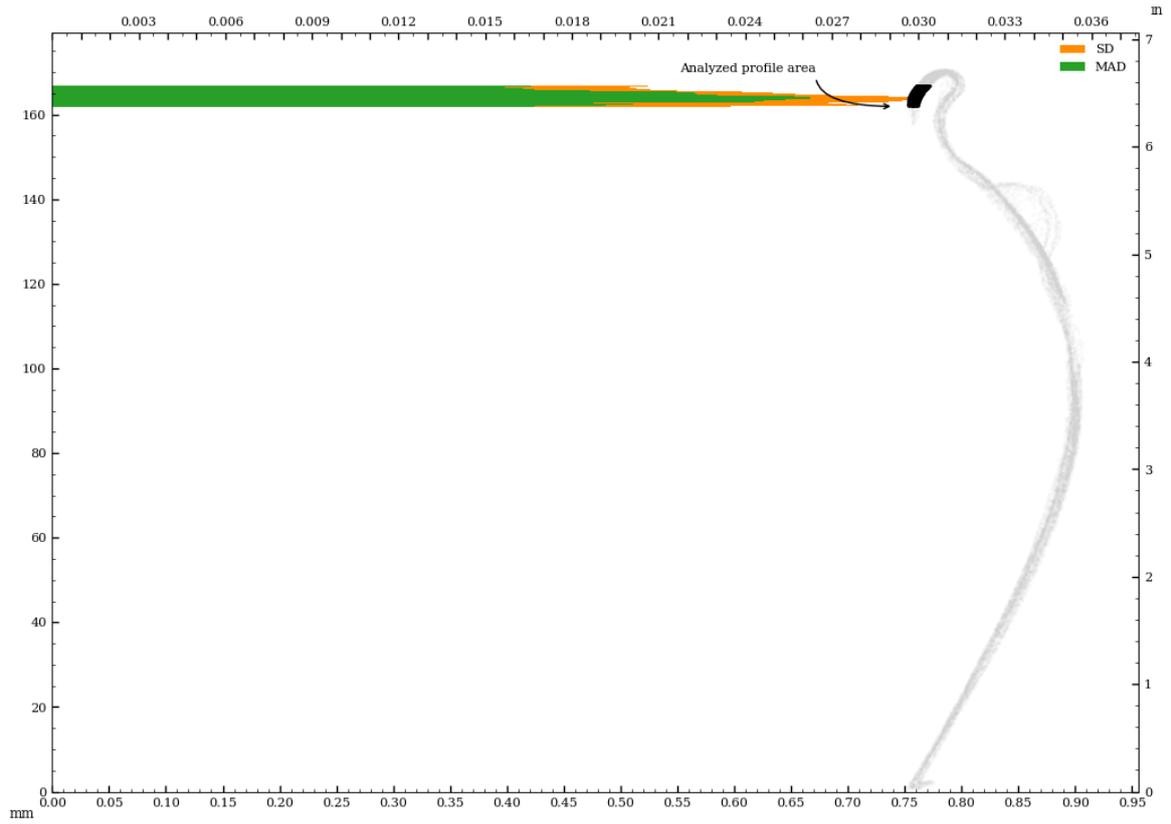

Figure 47: Circularity analysis of interior samples perpendicular to surface curvature

## Circularity analysis of interior surface - in z-plane
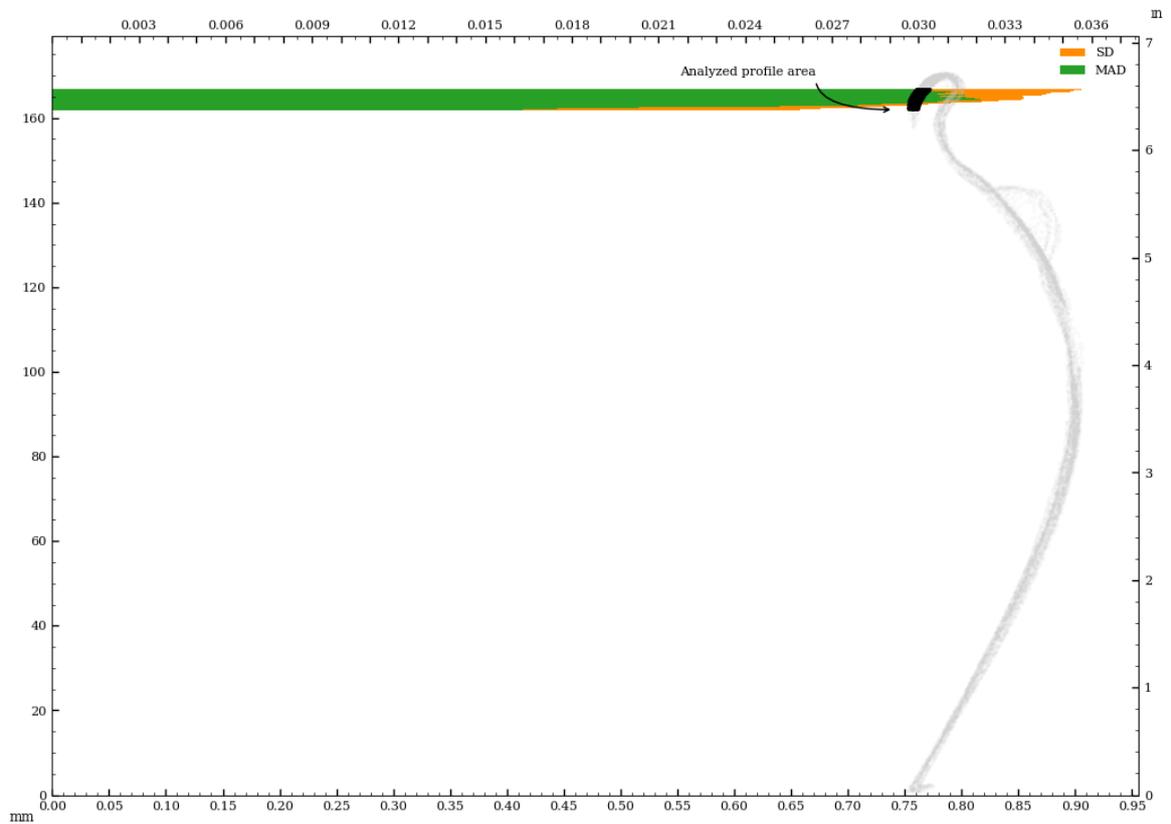
Figure 48: Circularity analysis of interior surface - in z-plane

Appendix B - Comparison Of Concentricity Measurements (Z-plane vs. surface-perpendicular)

Metric

Concentricity measurements perpendicular to surface curvature

Tag	Reference	Deviation	Sample size	Circle fit residuals analysis for sample listed in Tag column						
				Range full	Range inliers	SD full	SD inliers	MAD full	MAD inliers	Center (x,y)
		mm		mm	mm	mm	mm	mm	mm	μm
c01	z-axis	0.794	2735	3.565	3.361	0.788	0.758	0.526	0.518	280, −743
c02	z-axis	0.189	2557	2.883	2.122	0.625	0.498	0.334	0.310	−182, −52
c03	z-axis	0.205	2157	3.235	2.285	0.630	0.525	0.333	0.308	−149, 141
c04	z-axis	0.191	3575	3.474	3.474	0.820	0.820	0.486	0.486	190, −15
c05	z-axis	0.213	2276	1.724	1.724	0.397	0.397	0.292	0.292	−213, −16
c06	z-axis	0.900	3455	2.953	2.953	0.735	0.735	0.620	0.620	421, −796
c01	c06	0.150	2735	3.565	3.361	0.788	0.758	0.526	0.518	−141, 52

Concentricity measurements in z-plane

Tag	Reference	Deviation	Sample size	Circle fit residuals analysis for sample listed in Tag column						
				Range full	Range inliers	SD full	SD inliers	MAD full	MAD inliers	Center (x,y)
		mm		mm	mm	mm	mm	mm	mm	μm
c01	z-axis	1.190	4007	5.784	5.784	1.755	1.755	1.130	1.130	388, −1125
c02	z-axis	0.382	4118	3.545	2.650	0.780	0.632	0.450	0.417	−379, −49
c03	z-axis	0.193	2347	3.586	2.517	0.635	0.529	0.313	0.301	−127, 145
c04	z-axis	0.229	4207	3.677	3.677	0.876	0.876	0.524	0.524	227, −33
c05	z-axis	0.282	3011	1.844	1.844	0.460	0.460	0.353	0.353	−281, −15
c06	z-axis	0.964	3715	4.415	4.415	1.238	1.238	0.847	0.847	433, −862
c01	c06	0.267	4007	5.784	5.784	1.755	1.755	1.130	1.130	−44, −263

Concentricity measurements perpendicular to surface curvature

Tag	Reference	Deviation	Sample size	Circle fit residuals analysis for sample listed in Tag column						
				Range full	Range inliers	SD full	SD inliers	MAD full	MAD inliers	Center (x,y)
		in		in	in	in	in	in	in	thou
c01	z-axis	0.0313	2735	0.1404	0.1323	0.0310	0.0298	0.0207	0.0204	11.0, −29.3
c02	z-axis	0.0074	2557	0.1135	0.0836	0.0246	0.0196	0.0131	0.0122	−7.1, −2.0
c03	z-axis	0.0081	2157	0.1274	0.0900	0.0248	0.0207	0.0131	0.0121	−5.9, 5.5
c04	z-axis	0.0075	3575	0.1368	0.1368	0.0323	0.0323	0.0191	0.0191	7.5, −0.6
c05	z-axis	0.0084	2276	0.0679	0.0679	0.0156	0.0156	0.0115	0.0115	−8.4, −0.6
c06	z-axis	0.0354	3455	0.1163	0.1163	0.0289	0.0289	0.0244	0.0244	16.6, −31.3
c01	c06	0.0059	2735	0.1404	0.1323	0.0310	0.0298	0.0207	0.0204	−5.5, 2.1

Concentricity measurements in z-plane

Tag	Reference	Deviation	Sample size	Circle fit residuals analysis for sample listed in Tag column						
				Range full	Range inliers	SD full	SD inliers	MAD full	MAD inliers	Center (x,y)
		in		in	in	in	in	in	in	thou
c01	z-axis	0.0469	4007	0.2277	0.2277	0.0691	0.0691	0.0445	0.0445	15.3, −44.3
c02	z-axis	0.0151	4118	0.1396	0.1043	0.0307	0.0249	0.0177	0.0164	−14.9, −1.9
c03	z-axis	0.0076	2347	0.1412	0.0991	0.0250	0.0208	0.0123	0.0118	−5.0, 5.7
c04	z-axis	0.0090	4207	0.1448	0.1448	0.0345	0.0345	0.0206	0.0206	8.9, −1.3
c05	z-axis	0.0111	3011	0.0726	0.0726	0.0181	0.0181	0.0139	0.0139	−11.1, −0.6
c06	z-axis	0.0380	3715	0.1738	0.1738	0.0488	0.0488	0.0333	0.0333	17.0, −33.9
c01	c06	0.0105	4007	0.2277	0.2277	0.0691	0.0691	0.0445	0.0445	−1.8, −10.4